

Thermal evolution and sintering of chondritic planetesimals

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ABSTRACT

Aims. Radiometric ages for chondritic meteorites and their components provide information on the accretion timescale of chondrite parent bodies, and on cooling paths within certain areas of these bodies. However, to utilize this age information for constraining the internal structure, and the accretion and cooling history of the chondrite parent bodies, the empirical cooling paths obtained by dating chondrites must be combined with theoretical models of the thermal evolution of planetesimals. Important parameters in such thermal models include the initial abundances of heat-producing short-lived radionuclides (^{26}Al and ^{60}Fe), which are determined by the accretion timescale, and the terminal size, chemical composition and physical properties of the chondritic planetesimals. The major aim of this study is to assess the effects of sintering of initially porous material on the thermal evolution of planetesimals, and to constrain the values of basic parameters that determined the structure and evolution of the H chondrite parent body.

Methods. A new code is presented for modelling the thermal evolution of ordinary chondrite parent bodies that initially are highly porous and undergo sintering by hot pressing as they are heated by decay of radioactive nuclei. The pressure and temperature stratification in the interior of the bodies is calculated by solving the equations of hydrostatic equilibrium and energy transport. The decrease of porosity of the granular material by hot pressing due to self-gravity is followed by solving a set of equations for the sintering of powder materials. For the heat conductivity of granular material we combine recently measured data for highly porous powder materials, relevant for the surface layers of planetesimals, with data for heat conductivity of chondrite material, relevant for the strongly sintered material in deeper layers.

Results. Our new model demonstrates that in initially porous planetesimals heating to central temperatures sufficient for melting can occur for bodies a few km in size, that is, a factor of ≈ 10 smaller than for compact bodies. Furthermore, for high initial ^{60}Fe abundances small bodies may differentiate even when they had formed as late as 3–4 Ma after CAI formation. To demonstrate the capability of our new model, the thermal evolution of the H chondrite parent body was reconstructed. The model starts with a porous body that is later compacted first by ‘cold pressing’ at low temperatures and then by ‘hot pressing’ for temperatures above $\approx 700\text{ K}$, i.e., the threshold temperature for sintering of silicates. The thermal model was fitted to the well constrained cooling histories of the two H chondrites Kernouvé (H6) and Richardton (H5). The best fit is obtained for a parent body with a radius of 100 km that accreted at $t = 2.3\text{ Ma}$ after CAI formation, and had an initial $^{60}\text{Fe}/^{56}\text{Fe} = 4.1 \times 10^{-7}$. Burial depths of 8.3 km and 36 km for Richardton and Kernouvé can reproduce their empirically determined cooling history. These burial depths are shallower than those derived in previous models. This reflects the strong insulating effect of the residual powder surface layer, which is characterized by a low thermal conductivity.

Key words. Solar system: formation, planetary systems: formation, planetary systems: protoplanetary disks

1. Introduction

According to our present understanding of the formation of terrestrial planets, planetesimals from the size class of 100 km form an important transition state during the formation of protoplanets and planets (e.g. Weidenschilling & Cuzzi 2006; Nagasawa et al. 2007). These bodies are sufficiently big that heat liberated by decay of short lived radioactive nuclei, e.g. ^{26}Al , does not easily flow to the surface and radiates away. Instead they heat up and the bigger ones start to melt in their core region. The pristine dust material from the accretion disc undergoes in this way a number of metamorphic processes until it evolves into planetary material. A few such bodies representing this intermediate stage of the planetary formation process have survived in the asteroid belt and material from such bodies is available on earth as meteorites. Meteorites preserve in their structure and composition rather detailed information on the processes that

were at work during planetary formation. Recovering this information from these witnesses of the early history of our solar system requires to model the structure, composition, and thermal history of meteorite parent bodies in order to put the analytic results of laboratory investigations of individual meteorites into a more general context.

There are fundamental differences in the composition of ordinary and carbonaceous chondritic meteorites that are related to the absence or presence of ice, respectively, in the region of the protoplanetary disc where their parent bodies formed. We aim in this paper to study the parent bodies of ordinary chondrites. They were essentially ice-free, and are in this respect more similar to planetesimals in the inner solar system, where the terrestrial planets formed. In particular we concentrate on the H and L chondrites that form two rather homogeneous classes and seem each to descend from a single parent body in the asteroid belt.

The model calculations for the thermal evolution of asteroids done so far are reviewed by McSween et al. (2003) and by

Ghosh et al. (2006). Many of the calculations are based on the analytic solution of the heat conduction equation with constant coefficients for a spherical body heated by a homogeneously distributed and exponentially decaying heat source (^{26}Al) given by Miyamoto et al. (1981). Such models have the advantage of being simple and easily applicable for discussions of special problems, but they cannot be extended to more realistic cases where material properties like heat conduction, specific heats and others are neither spatially nor temporally constant, or to include additional physics. It was possible, however, to show that H and L chondrites of petrologic classes 3 to 6 originate from bodies of about 100 km size, heated by radioactive decay of short lived nuclei, and that the different petrologic classes correspond to layers at different depths within the same body which experienced different thermal histories during the initial heating and subsequent cooling of the body (Göpel et al. 1994; Trierloff et al. 2003; Kleine et al. 2008; Harrison & Grimm 2010).

If more physics is to be included in a model a numerical solution of the basic set of equations is necessary. One of the first models of this kind was the model calculation by Yomogida & Matsui (1984) that used data for the temperature and porosity dependence of material properties which they determined by laboratory measurements on H and L chondrite material (Yomogida & Matsui 1983). A central point of this model calculation was that it addressed for the first time quantitatively the process of sintering of the initially strongly porous material under the action of pressure resulting from self-gravity once the body is heated to high temperatures ($\geq 700\text{ K}$). As a result, the body develops a strong zoning of the material properties: A highly consolidated core with high thermal conductivity if temperature and pressure become sufficiently high during the course of the thermal evolution of the body, and a porous outer layer with low heat conductivity where temperatures and pressures never climbed to the level where compaction by sintering becomes possible.

This model shows distinct basic differences to a model with constant coefficients like that of Miyamoto et al. (1981) since it has an extended inner region with an only slow outwards drop of temperature where heat conductivity is high, and a rather shallow outer layer where temperature rapidly drops to the outer boundary temperature. The results for the depths of formation of different petrologic types and the predicted spatial extent of such zones are very different in the models of Miyamoto et al. (1981) and Yomogida & Matsui (1984). This demonstrates the importance of including the consolidation of granular material by 'hot pressing' and the resulting changes of thermal conductivity in the models. Unfortunately the results of Yomogida & Matsui (1984) are somewhat impaired by the fact that the important heating source ^{26}Al was not included in the calculation. In the sequel the sintering processes seem to have been included in the modelling of thermal evolution of asteroids only in the calculations of Akridge et al. (1997) and of Senshu (2004). Other studies of the blanketing effect of porous outer layers on thermal evolution (Akridge et al. 1998; Hevey & Sanders 2006; Sahijpal et al. 2007; Gupta & Sahijpal 2010) assume the consolidation of such layers at some characteristic temperature, but do not include this process as part of the model calculation.

In this paper we study the thermal history of the parent bodies of ordinary chondrites using new data for the thermal conductivity of granular material (Krause et al. 2011a,b) and on the compaction by cold isostatic pressing before the onset of sintering (Güttler et al. 2009). The modelling of the sintering process is based on the same kind of theory (Rao & Chaklader 1972) as in Yomogida & Matsui (1984). This theory does not correspond

Table 1. Basic mineral species considered for calculation of properties of chondrite material, their atomic weight A , mass-density ρ , and abbreviation of mineral name.

species	composition	A	ρ	Abbr.
Forsterite	Mg_2SiO_4	140.69	3.22	Fo
Fayalite	Fe_2SiO_4	203.78	4.66	Fa
Enstatite	MgSiO_3	100.39	3.20	En
Ferrosilite	FeSiO_3	132.32	3.52	Fs
Wollastonite	CaSiO_3	116.16	2.91	Wo
Anorthite	$\text{CaAl}_2\text{Si}_2\text{O}_8$	277.41	2.75	An
Albite	$\text{NaAlSi}_3\text{O}_8$	263.02	2.63	Ab
Orthoclase	KAlSi_3O_8	278.33	2.55	Or
Iron	Fe	55.45	7.81	Iron
Nickel	Ni	58.69	8.91	Nkl
Troilite	FeS	87.91	4.91	Tr

to the more recent approaches used for modelling of hot pressing in technical processes (e.g. Arzt et al. 1983; Fischmeister & Arzt 1983; Larsson et al. 1996; Storåkers et al. 1999), but it seems more appropriate for the lower pressure regime encountered in asteroids.

The main purpose of this paper is to develop improved models for the thermal history of parent bodies of ordinary chondrites and to compare the model results with cooling histories of H and L chondrites of different petrologic types determined from thermochronological methods in cosmochemistry. This allows to better constrain the size of the parent bodies and their formation times.

2. Thermal history of chondrite parent bodies

The heat source for early differentiation and metamorphism of meteorite parent bodies was decay heat of short-lived nuclides like ^{26}Al or ^{60}Fe (Göpel et al. 1994; Trierloff et al. 2003; Kleine et al. 2008; Bouvier et al. 2007). If planetesimals are larger than tens of km, the maximum degree of internal heating is given by the initial ^{26}Al abundance, i.e., mainly formation time. Planetesimals formed at $\approx 2\text{ Ma}$ after calcium-aluminium rich inclusions (CAIs — commonly regarded as oldest objects in the solar system), heat up without differentiation, yielding thermally metamorphosed chondritic parent bodies (ordinary chondrites, enstatite chondrites, or more strongly heated Acapulcoites and Lodranites). Primitive chondrites (such as petrologic type 3) can survive in the outer cool layers of larger parent bodies (following the onion shell model, see, e.g., Göpel et al. 1994; Trierloff et al. 2003), or in bodies that never grew larger than 10 – 20 km in size (Hevey & Sanders 2006; Yomogida & Matsui 1984), or in bodies that formed relatively late.

Such scenarios can be verified via their thermal history and cooling paths. These paths can be evaluated by a variety of thermochronological methods applying chronometers with different closure temperatures, which means the temperature where no parent or daughter nuclide is lost from their host minerals. The Hf-W dating method (e.g. Kleine et al. 2005, 2008) is useful for cooling below 1050 to 1150 K. The closure temperature for the U-Pb-Pb system in phosphates is $\approx 720\text{ K}$ (e.g. Göpel et al. 1994; Bouvier et al. 2007), Ar-Ar ages reflect the cooling below $\approx 550\text{ K}$ for oligoclase feldspar. The annealing temperature for ^{244}Pu fission tracks (e.g. Pellas et al. 1997; Trierloff et al. 2003) in orthopyroxene is 550 K, for the phosphate merrillite $\approx 390\text{ K}$. The latter yield a relative cooling rate between 550 and 390

Table 2. Typical mineral composition of chondrites, mass-densities ρ of components, mass-fractions X_{\min} of minerals, and mass-fractions X_{el} of the elements that release heat by radioactive decays (data for X_{\min} from Yomogida & Matsui 1983).

species	H-chondrite			L-chondrite			element	H-chondrite	L-chondrite
	composition	ρ g cm ⁻³	X_{\min}	composition	ρ g cm ⁻³	X_{\min}		X_{el}	X_{el}
Olivine	Fo ₈₀ Fa ₂₀	3.51	0.37	Fo ₇₅ Fa ₂₅	3.58	0.49	Al	9.10×10^{-3}	8.95×10^{-3}
Orthopyroxene	En ₈₃ Fs ₁₇	3.25	0.25	En ₇₈ Fs ₂₂	3.27	0.23	Fe	2.93×10^{-1}	2.26×10^{-1}
Clinopyroxene	En ₄₉ Fs ₆ Wo ₄₅	3.09	0.05	En ₄₈ Fs ₈ Wo ₄₄	3.10	0.06	K	7.07×10^{-4}	7.07×10^{-4}
Plagioclase	Ab ₈₂ Or ₆ An ₁₂	2.64	0.08	Ab ₈₄ Or ₆ An ₁₀	2.64	0.08	Th	5.16×10^{-8}	5.72×10^{-8}
Nickel-iron	Ir ₉₂ Ni ₈	7.90	0.20	Ir ₈₇ Ni ₁₃	7.95	0.09	U	2.86×10^{-8}	3.17×10^{-8}
Troilite	Tr	4.91	0.05	Tr	4.91	0.05			
Average = ρ_{bulk}		3.78			3.59				

K for the respective rock (e.g. Pellas et al. 1997; Trierloff et al. 2003). Another method to determine cooling rates between 800 and 600 K are metallographic cooling rates, which use Fe-Ni diffusion profiles in metal grains consisting of the two different Fe/Ni phases kamacite and taenite (Herpfer et al. 1994; Hopfe & Goldstein 2001, e.g.). These data are the basis for the simulation of the cooling of chondritic parent bodies in Sect. 8.

3. Composition of planetesimal material

3.1. Mineral composition of planetesimal material

From the pristine dust material in the accretion disk, that is formed simultaneously with the formation of a new star, finally planetesimals are formed by a complicated agglomeration process. This process is not modelled in our calculation (for a review on this part of the problem see, e.g., Nagasawa et al. 2007). We concentrate here on the evolution of the internal constitution of the planetesimals, the successors of which can still be found in the asteroid belt. In particular we concentrate on the class of planetesimals that are the parent bodies of the H- and L-chondrites. Their composition is well known from studies of meteorites. The matrix and chondrules that form the material of the ordinary chondrites consist of a mixture of minerals that themselves in most cases are solid solutions of a number of components. We consider an average composition for the material contained in the parent bodies of the H- and of the L-chondrites that concentrates on the few main constituents that represent almost 100% of the matter. The many more additional compounds with small abundances found in the material are not important for the bulk properties of those materials that determine the constitution of the planetesimals and their evolution.

The pure mineral components used in our model for the composition of planetesimals and their mass-densities are listed in Table 1. The mixture of minerals that is assumed to form the planetesimal material is listed in Table 2. The composition is given in the notion where, e.g., Fo₈₀Fa₂₀ denotes that 80% of all basic building blocks of the mineral correspond to forsterite and 20% to fayalite. The quantity X_{\min} denotes the mass fraction of the component in the mixture. The composition of the mixture components and the fractions X_{\min} are taken from Yomogida & Matsui (1983); the average composition of chondrites given by Jarosewich (1990) is essentially the same, only the Fe and Al mass-fractions are slightly less than in Yomogida & Matsui (1983).

The density of the solid solutions given in the table is simply calculated as average of the densities of the pure components,

Table 3. Some properties of chondrules and matrix in H and L chondrites (data from Scott (2007)).

		H	L
Chondrules	Vol. %	60–80	60–80
Chondrule diameter (ave.)	mm	0.3	0.5
Matrix	Vol. %	10–15	10–15

weighted with their mole fractions in the solid solution. This assumes that non-ideal mixing effects are too small as that they need to be considered for our calculations. The average density ρ_{bulk} of the mixture is calculated from

$$\rho_{\text{bulk}} = \left(\sum_i \frac{X_{\min,i}}{\rho_i} \right)^{-1}. \quad (1)$$

This is the density of the consolidated meteoritic material, i.e., without pores.

Table 2 presents mass-fractions X_{el} of the elements for which radioactive isotopes of sufficient abundance exist that their energy release during decay contributes significantly to the heating of the planetesimals. The element abundances used for the calculation are from Lodders et al. (2009).

3.2. Granular nature of the material

The main constituents present in chondritic meteorites are chondrules and a matrix of fine dust grains. The typical relative abundance of these constituents is shown in Table 3, they have typical sizes of micrometer in the case of relatively unprocessed matrix, and typical sizes of millimetres in the case of chondrules, with variations specific to each chondrite group (Scott 2007). Though chondrules may also contain fine grained mineral assemblages, they entered the meteorite parent body as solidified melt droplets after they formed by unspecified flash heating events in the solar nebula.

The size of the fine dust grains of the matrix before compaction and sintering of the meteoritic material is not known. The observed sizes of matrix particles may be not representative because coarsening may have occurred during heating of the parent body (Ostwald ripening). Probably the very fine granular units in interplanetary dust particles (IDPs) give a hint to the pristine size of dust particles in protoplanetary discs before incorporation into the forming bodies of the solar system. IDPs seem to represent cometary dust (Bradley 2010) and this seems

to be the least processed dust material handed down from the early Solar Nebula. The study of Rietmeijer (1993) shows that the granular units forming IDPs are sub-micrometer sized, most of them having diameters smaller than $0.5 \mu\text{m}$ and many being nano-meter sized, $\ll 0.1 \mu\text{m}$, with a small population ranging in size up to several μm . Typical particle radii then are roughly of the order of $0.1 \mu\text{m} \dots 0.2 \mu\text{m}$.

It is generally assumed that the planetesimal material initially is very loosely packed with a high degree of porosity. As porosity ϕ we denote the *volume fraction not filled* by solid dust material. The volume not filled by the solids is called the pore space or the pores. The pores may form an interconnected network of voids and channels at high porosity, $\phi \lesssim 1$, or isolated voids at low porosity, $\phi \ll 1$. The pores may be empty (vacuum) or may be filled with gas or something else. If there are no pores, the material is called compact.

The compact solid material has density ϱ_{bulk} . This material is a complex mixture of minerals, that is described in Sect. 3.1. The porous material has density

$$\varrho = \varrho_{\text{bulk}}(1 - \phi) + \varrho_p \phi, \quad (2)$$

where ϱ_p is the density of the material in the pores. If the pores are filled with gas then ϱ_p is small enough that we may assume $\varrho_p = 0$. At sufficient low temperatures the pores may alternatively be filled by water and ice in which case ϱ_p may not be neglected, but here we do not consider such cases. Then

$$\varrho = \varrho_{\text{bulk}}(1 - \phi). \quad (3)$$

Besides porosity ϕ we also consider the filling factor

$$D = 1 - \phi. \quad (4)$$

Then

$$\varrho = \varrho_{\text{bulk}} D. \quad (5)$$

For this reason D is also called the *relative density* of the porous material.

The porous material may approximately be described as a packing of spheres. With respect to the chondrules this is not unrealistic, because they show nearly spherical shape. For the matrix grains this may be taken as a rough approximation to describe some basic properties of the packing. For a random packing of equal sized spheres, Arzt (1982) found a relation between the coordination number Z , i.e., the average number of contact points of a particle with its neighbours, with the filling factor or relative density D :

$$Z(D) = Z_0 + C \left(\left(\frac{D}{D_0} \right)^{1/3} - 1 \right) \quad (6)$$

Here, $Z_0 = 7.3$ and $D_0 = 0.64$. These values refer to the coordination number of a random dense packing of spheres (cf. Jeager & Nagel 1992). The constant $C = 15.5$ is the slope of the radial density function (distribution of centre distances). The approximation hold up to $D > 0.9$.

For a packing of equal sized spheres it is found that there are two critical filling factors. One is the random close packing with a filling factor of $D = 0.64$, i.e., a porosity of $\phi = 0.36$ (Scott 1962; Jeager & Nagel 1992), and an average coordination number $Z = 7.3$. Its formation requires taping or joggling at the material. The other one is the loosest close packing that is just stable under the application of external forces (in the limit of vanishing force), which has $D = 0.56$ or $\phi = 0.44$ (Onoda & Liniger

1990; Jeager & Nagel 1992) and average coordination number $Z \approx 6.6$. With respect to chondritic material this means that volume filling factors of more than $D = 0.64$ for chondrules, like that given in Table 3, require that compaction by sintering or compaction by crushing of particles due to strong pressure occurred.

For volume filling factors of chondrules between the random close packing ($D = 0.64$) and the random loose packing ($D = 0.56$) some pre-compaction by applied forces occurred. The high volume filling factors of chondrules in the material of the chondrites, hence, shows that this material was already significantly compressed. It is not possible to reconstruct from this the initial properties of the material in the bodies that contributed to the growth of the parent bodies. We have to estimate this somehow.

At the basis of the planetesimal formation process there stands the agglomeration of fine dust grains like that found in IDPs into dust aggregates of increasing size. Such an agglomerated material from very fine grains that was not subject to any pressure has porosity as high as $\phi \approx 0.8 \dots 0.9$ (e.g. Yang et al. 2000; Krause et al. 2011a). The number of contacts of a particle to neighbouring particles then is on the average equal to about two, i.e., the fine dust grains form essentially chain like structures. Such high-porosity material seems to be preserved in some comets (Blum et al. 2006).

Collisions of dust aggregates during the growth process of planetesimals leads to compaction of the material. The experiments of Weidling et al. (2009) have shown that the porosity can be reduced to $\phi \approx 0.64$ (or even lower, see Kothe et al. 2010) by repeated impacts. This porosity is still higher than the random loose packing and, hence, is not guaranteed to be mechanically stable. The average coordination number is $Z \approx 5$. Lower porosities of $\phi \lesssim 0.4$ were obtained by applying static pressures of more than 10 bar (Güttler et al. 2009). Since the planetesimals form by repeated growth process by collisions with other growing planetesimals and impact velocities can be rather high we assume in the model calculations that the initial porosity of the material from which the parent bodies of the asteroids formed is already compacted to some extent and assume a porosity of the order of $\phi = 0.6 \dots 0.5$.

4. Internal pressure within planetesimals

4.1. Hydrostatic equilibrium

The planetesimals are subject to the mutual gravitational interaction between their different parts from which there results an inward directed gravitational force at each location. As long as the material is highly porous and was not yet subject to sintering processes, the granular material may start to flow (by rolling and gliding of the powder particles) and evolve into a state with the densest packing of the granular material. If the planetesimal material is approximated by a random packing of spheres of equal size its porosity in this state would be about $\phi = 0.37$ (Yang et al. 2000). In this state the forces due to the mutual gravitational attraction of all other particles are compensated by the reactive forces due to internal stresses that are build up within the particles as result of the forces acting between contact points to neighbouring particles. The material then can exist in a state of hydrostatic equilibrium with no relative motion between grains. This equilibrium state, however, is of a rather labile character because at contacts points between grains stresses may be build up that are strong enough that particles may break apart into smaller pieces and some further compaction of the material is possible

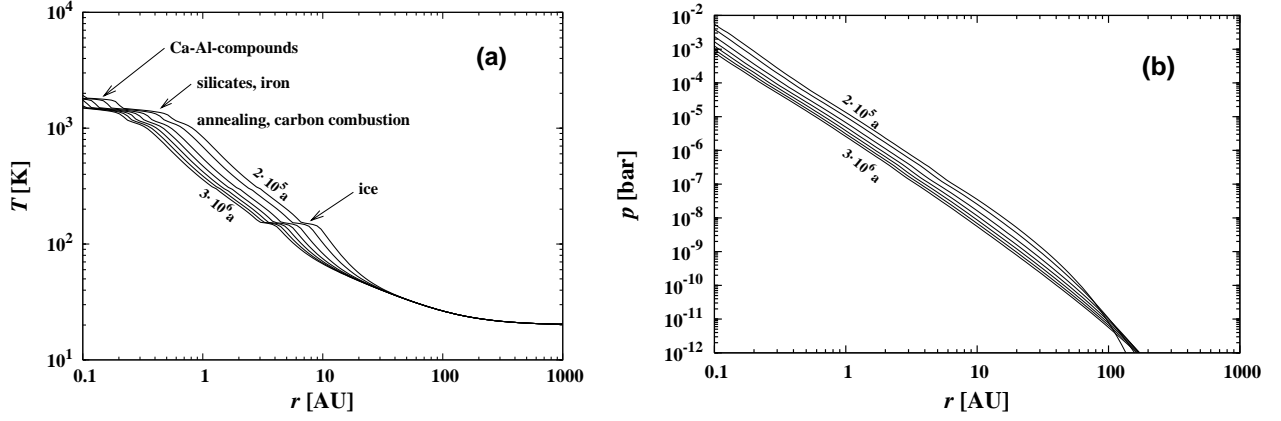


Fig. 1. Variation of (a) mid-plane temperature and (b) pressure with distance from the star at different evolutionary epochs (0.2 Ma and from 0.5 Ma to 3 Ma in steps of 0.5 Ma) in a model for the evolution of the Solar Nebula (one-zone α -model). They define the outer boundary conditions for a planetesimal embedded in an accretion disk. In the left part the regions are indicated where the disappearance of an important absorber results in an extended region of nearly constant mid-plane temperature.

by application of high pressures. For planetesimal material this kind of compaction is probably only relevant for impact problems. During the gradual build-up of planetesimals, temperatures become already high enough by internal heating for sintering by internal creep to occur before really high pressures are built up by which the material may be crushed.

We assume in our further considerations that during the very initial build-up of planetesimals the initially very loosely packed granular material, under the action of its own gravitational attraction and/or during collisions with other planetesimals, has already evolved by granular flow to a state where all particles have a sufficient number of contacts to neighbours such that further relative motions are effectively blocked ($\phi \lesssim 0.44$). Further compaction then requires considerable pressures because particles have to be broken for this. Additionally we neglect that the planetesimals may rotate and therefore neglect any deformation of the body resulting from this. Then we may assume that the planetesimals have spherically symmetric structure and the distribution of internal pressure in the porous dust ball is described by the well known hydrostatic pressure equation

$$\frac{dp}{dr} = -\frac{GM_r}{r^2} \varrho \quad (7)$$

where

$$M_r = 4\pi \int_0^r dr' r'^2 \varrho(r'). \quad (8)$$

The density ϱ is the mass-density of the material.

As long as a planetesimal is embedded in an accretion disk it is subject to the external pressure in the disk. The equation of the hydrostatic pressure stratification in the planetesimal therefore has to be solved with the outer boundary condition at the outer radius R

$$p(R) = p_{\text{ext}}, \quad (9)$$

with p_{ext} being the pressure in the accretion disk. The pressure in the midplane of the Solar Nebula at a number of instants as calculated from an evolution model of the disk (Wehrstedt & Gail 2002, 2008) is shown in Fig. 1b. This defines the outer boundary condition p_{ext} . After dissipation of the accretion disk one has to use

$$p(R) = 0 \quad (10)$$

instead.

In order to estimate the magnitude of pressure let us consider a body with constant density ϱ . We have in this case

$$M_r = \frac{4\pi}{3} \varrho r^3. \quad (11)$$

For a body with radius R and external pressure p_{ext} integration of the pressure equation yields

$$p(r) = p_{\text{ext}} + \frac{4\pi}{3} G \varrho^2 \int_r^R dr' r' \quad (12)$$

and then

$$p(r) = p_{\text{ext}} + \frac{2\pi}{3} G \varrho^2 R^2 \left(1 - \left(\frac{r}{R} \right)^2 \right). \quad (13)$$

For the central pressure p_0 at $r = 0$ we have numerically

$$p_0 = p_{\text{ext}} + 1.258 \times 10^{-2} \left(\frac{\varrho}{3 \text{ g cm}^{-3}} \right)^2 \left(\frac{R}{1 \text{ km}} \right)^2 [\text{bar}]. \quad (14)$$

The external pressure in the accretion disk is shown in Fig. 1b and we see that already for bodies as small as 1 km radius the central pressure in the body is significantly higher than the pressure in the accretion disk. In bodies with radii of 10 km and bigger one encounters central pressures of the order of 1 bar and higher.

4.2. Isostatic pressing of the granular material

The behaviour of granular material under pressure may be rather complex. This has been discussed by Güttler et al. (2009) with particular emphasis on impact processes during planetesimal growth. They performed also laboratory experiments for the behaviour of fine grained material under the action of static pressure and how porosity is reduced if the material is compacted by pressing. They derived a relation between the applied pressure p and the relative density (filling factor) D that is observed after the material has come to rest¹

$$D(p) = 0.58 - 0.46 \left[\left(\frac{p}{p_m} \right)^{1.72} + 1 \right]^{-1}, \quad p_m = 0.13 \text{ bar}. \quad (15)$$

¹ Note that they denote the filling factor as ϕ

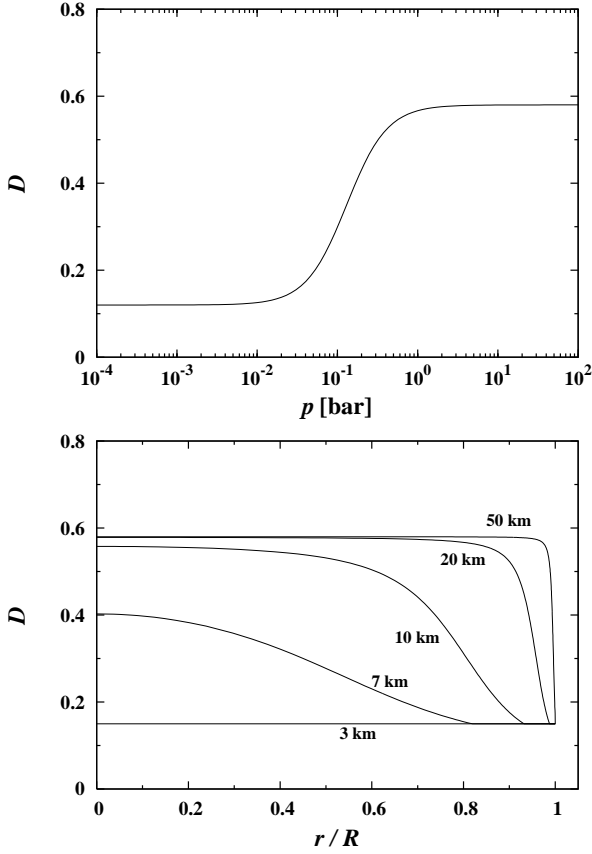


Fig. 2. Relation between relative density (filling factor) D and maximum experienced pressure for isostatic pressing (top) and run of relative density within planetesimals of the indicated size (bottom) that results from cold pressing due to self-gravity.

This relation only holds for $D > 0.15$ because $D \approx 0.15$ was the initial value of the relative density of the material in the experiments before pressing. Its validity is also limited to pressures where the granular material is not yet compacted to the relative density $D \approx 0.64$ of a random densest packing of equal sized spheres.

The meaning of Eq. (15) is that it describes the porosity $\phi = 1 - D$ of a fine powder that experienced the maximum pressure p . With respect to the material in a planetesimal it gives the porosity distribution within the planetesimal as function of depth for those parts where Eq. (15) predicts a lower porosity than the porosity of the surface material. The latter is determined by the continued impact processes during particle growth that result also in a compaction of the powder material (Weidling et al. 2009), a process, however, that is not described by Eq. (15). The porosity ϕ_{srf} of the surface layer material has to be described in a different way. Hence we have to determine the porosity in the planetesimal from the following equation

$$\phi = \begin{cases} 1 - D(p) & \text{if } D(p) > 1 - \phi_{\text{srf}} \\ \phi_{\text{srf}} & \text{else} \end{cases} \quad (16)$$

This holds before sintering (see Sect. 6) becomes active. Figure 2 shows in the upper part the variation of relative density D with maximum experienced pressure according to Eq. (16). The lower part shows as example the distribution of relative density within planetesimals with 3 km to 50 km radius resulting from cold isostatic pressing, if no upper limit for the surface porosity is prescribed. The solutions are obtained by integration of Eq. (7) with

Eqs. (5) and (15) as equation of state. This shows that up to planetesimal sizes of about 7 km the material is not substantially compacted by self-gravity of the body. For planetesimals bigger than 10 km most part of the body is already compacted by cold isostatic pressing due to self-gravity to a density close to that of the densest random packing of equal sized spheres. Only a rather shallow surface layer of highly porous material remains in such bodies. This is anyhow evident, but here a quantitative prediction can be made.

4.3. Exosphere

During the first few million years all bodies in a nascent planetary system are immersed in the protoplanetary accretion disk. Sufficiently massive bodies are able to gravitationally bind some of the gas. The minimum requirement for this is that the escape velocity of a gas particle from the surface of a body exceeds its average kinetic energy of thermal motion corresponding to the disk temperature

$$\frac{2GM_R}{R} > \frac{kT}{m_g}, \quad (17)$$

where R is the planetesimal radius and m_g the average mass of the gas particles. From this one has for the lower limit of the planetesimal radius from which on gravitational bonding of an atmosphere starts to become possible

$$R_{\text{atm}} = \frac{2GM_R m_g}{kT}. \quad (18)$$

For a body with constant density ϱ this means that the radius has to exceed a radius of

$$R_{\text{atm}} = \sqrt{\frac{3kT}{8\pi G \varrho m_g}} = 650 \left(\frac{T}{300 \text{ K}} \frac{3g \text{ cm}^{-3}}{\varrho} \right)^{\frac{1}{2}} \text{ km} \quad (19)$$

in order to gravitationally bind gas from the accretion disc and increase the gas pressure at their surface over the local pressure in the disk. This is only relevant for protoplanets with radii $R \gtrsim 1000 \text{ km}$.

5. Temperature structure of planetesimals

5.1. Heat conduction equation

For the kind of bodies that we will consider, the material has the structure of granular matter. The internal structure of such kind of material is not isotropic and its properties are subject to strong local variations on the scale of particle sizes. As a result the temperature also will show local variations on the same length scales. The particles that form the granular material, however, are very small and in particular they are extremely small compared to typical length scales over which macroscopic properties of the bodies may vary. In this case we may average the microscopic properties of the material and also the temperature over volumes that contain a big number of particles and at the same time have dimensions small to the characteristic scale lengths for changes of the values of variables like average temperature T or average density ϱ . Then we work only with such average quantities, for which we can assume that they are isotropic after averaging over all possible particle orientations.

With this approximation the equation of energy conservation for a spherically symmetric body, expressed as an equation for

the temperature T of the matter, averaged over the microscopic fluctuations, is

$$\varrho c_v \frac{dT}{dr} + \frac{1}{r^2} \frac{\partial}{\partial r} r^2 q_r = +\varrho h - P \frac{d}{dt} \frac{1}{\varrho} + \varrho v_r F_r, \quad (20)$$

where c_v is the average specific heat of the granular material per unit mass, q_r is the radial component of the average heat flow vector, h is the average source term for heat production or consumption per unit mass, the pdV -term is the compressional work done per unit mass, and the last term is the work done by external forces. It is assumed that the external forces, F_r , are species independent and that no differential motion between the components of the material occurs (flow of gas or water through the porous matrix is presently not considered). The last two terms have not been considered so far in model calculations for thermal evolution of asteroids since they are negligible if the material is practically incompressible. However, if sintering is considered, the material becomes strongly compressed during the course of evolution and these terms have to be included.

The quantity v_r is the uniform radial velocity of the mixture components. If shrinking of the body by sintering is the only kind of motion of the otherwise stationary structure of the body, the velocity v_r is obtained by differentiation of Eq. (8) for fixed M_r with respect to time. There follows

$$v_r = -\frac{1}{r^2} \int_0^r dr' r'^2 \frac{\partial \varrho}{\partial t}. \quad (21)$$

We will consider models of planetesimals that are in hydrostatic equilibrium without internal flows. There may be some very slow radial motion of the matter if the material starts to shrink by sintering at high temperatures. This kind of extremely slow motion is completely negligible in the substantial derivatives $d/dt = \partial/\partial t + v_r \partial/\partial r$ in Eq. (20). However, one consequence of shrinking is not negligible: If the body shrinks the gravitational potential energy decreases and the corresponding amount of energy is transferred to the matter as heat. This is described by the term $\varrho v_r F_r$ where F_r is the local gravitational acceleration

$$g = -\frac{GM_r}{r^2}. \quad (22)$$

The term corresponding to the work done by the forces has to be retained. With this approximation we have the following equation for the temperature

$$\varrho c_v \frac{\partial T}{\partial r} + \frac{1}{r^2} \frac{\partial}{\partial r} r^2 q_r = +\varrho h - P \frac{\partial}{\partial t} \frac{1}{\varrho} - \varrho v_r \frac{GM_r}{r^2}, \quad (23)$$

The variation of ϱ with time is discussed in Sect. 6.

The heat flow vector has contributions from a number of processes. For the solid component of the material there is a contribution from heat conduction by phonons or, in the case of electric conductors (e.g. iron), from conduction electrons. For a porous material there is also a contribution from the heat conduction by the gas in the pores. If the material is translucent then one has also to consider a contribution to heat conduction by radiative transfer. All these processes have the property, that their contribution to the total heat flow is proportional to the gradient of the temperature. Generally the coefficient of proportionality is a second rank tensor, except if the properties of the material are isotropic, in which case it degenerates to a simple scalar factor. For granular material the local transport properties for heat are by no means isotropic. We assume, however, that after averaging the average heat flow vector is proportional to the gradient of

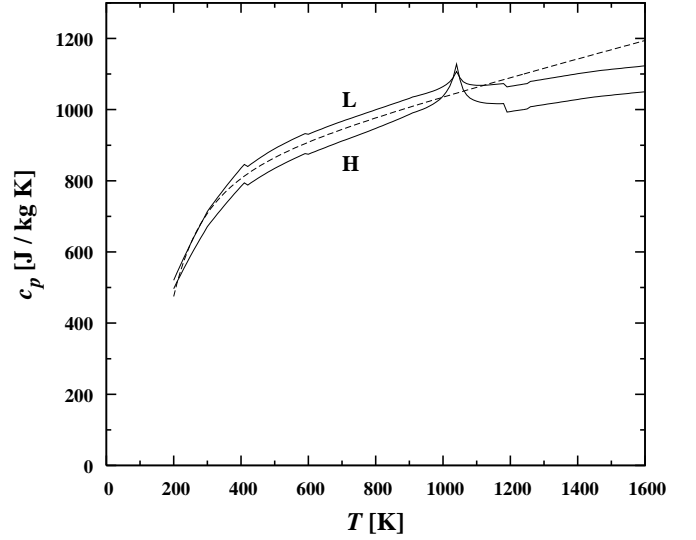


Fig. 3. Specific heat of planetesimal material for mineral mixtures of H chondrites and L chondrites. Dotted line is the analytic approximation of Yomogita & Matsui (1984).

the average temperature. The radial component of the heat flow vector then takes the specific form

$$q_r = -K \frac{\partial T}{\partial r} \quad (24)$$

with some average heat conduction coefficient K that is different for each of the different transport processes.

The essential material properties that enter into equation (23) are the specific heat per unit mass, c_v , the heat conductivity K , and the heat production. In the following subsections we describe how we determine these quantities for the material of the parent bodies of ordinary chondrites.

The body is also subject to heat and matter exchange with its environment. This is treated by defining appropriate boundary conditions for Eq. (23) that are discussed after our discussion of the material properties.

5.2. Heat capacity of material

The heat capacity c_v of a mineral mixture is simply the weighted sum of the heat capacities of its components. It is calculated in our model calculations from

$$c_v = \sum_i X_{\min,i} c_{v,i}, \quad (25)$$

where $X_{\min,i}$ is the mass-fraction of the i -th component in the mixture of solid components and $c_{v,i}$ the heat capacity per unit mass of component i . The quantities $X_{\min,i}$ are given in Table 2. Since we intend to consider bodies of a size of no more than a few 100 km, pressures remain below the kbar-range (see Eq. 14) and compression of solid material under pressure is negligible because of the low compressibility of minerals. Under these conditions there is no significant difference between c_p and c_v and we may use c_p instead of c_v . For our model calculations data for $c_{p,i}(T)$ are taken from the compilation of Barin (1995) that gives the heat capacities c_p per mole. These quantities are converted to heat capacity per unit mass by dividing by the mole mass M_i of species i :

$$c_v = \sum_i X_{\min,i} \frac{c_{p,i}}{M_i}. \quad (26)$$

Table 4. Data for calculating heating rates by decay of radioactive nuclei.

Species	f	E [MeV]	τ [a]	h W kg ⁻¹
²⁶ Al	5.1×10^{-5}	3.188 (1)	1.0×10^6	1.67×10^{-7}
⁶⁰ Fe (high)	1.6×10^{-6}	2.894 (1)	3.8×10^6	2.74×10^{-8}
(low)	4.2×10^{-7}			
⁴⁰ K	1.5×10^{-3}	0.693 (2)	1.8×10^9	2.26×10^{-11}
²³² Th	1.00	40.4 (2)	2.0×10^{10}	1.30×10^{-12}
²³⁵ U	0.24	44.4 (2)	1.0×10^9	3.66×10^{-12}
²³⁸ U	0.76	47.5 (2)	6.5×10^9	1.92×10^{-12}

Sources: (1) Finocchi & Gail (1997), (2) Van Schmus (1995)

Values of c_v for the required temperatures are determined by interpolation in the tables for $c_{p,i}$. The heat capacity for solid solutions is calculated as weighted mean of the heat capacities of the pure components taking their mole fractions as weights.

The variation of the specific heat of the mixture is shown in Fig. 3. Since some of the minerals suffer structural transitions at certain temperatures and since c_p of iron has a cusp at the Curie-temperature of 1042 K, the temperature variation of c_p shows some kinks and jumps (cf. also Ghosh & McSween 1999). They might be sources of numerical problems. For comparison the figure also shows the analytic approximation for c_p for the bulk material given by Yomogida & Matsui (1984). This is an alternative if the jumps in the temperature variation of c_p result in numerical problems, but in our calculations it was not necessary to take recourse to this approximation.

5.3. Heating by radioactive nuclei

Next we consider the source term h in Eq. (23). There are essentially two different kinds of sources and sinks of heat within the planetesimal bodies. One source is the energy liberated during decay of radioactive isotopes of a number of elements. The other one is consumption of energy during melting of planetesimal material or liberation of energy during solidification of the melt. Melting is not considered because we aim to study parent bodies of undifferentiated meteorites.

The main sources of heat input by radioactives during the early heating up of planetesimals and the subsequent cooling phase are decay of ²⁶Al and possibly ⁶⁰Fe (cf. the discussion in Ghosh et al. 2006). More long-lived radioactive nuclei, essentially ²³²Th, ^{235,238}U, and ⁴⁰K, are responsible for the later long-term evolution of the temperature. For the nuclei decaying by β -decay (²⁶Al, ⁶⁰Fe, ⁴⁰K) the energy of the fast electrons and of the emitted γ -photons is absorbed within the planetesimal material and is converted to heat, while the neutrinos leave the bodies and carry away their part of the energy. For the nuclei decaying by α -decay the whole decay energy is absorbed by the planetesimal material. We assume that no chemical differentiation occurs in the bodies that we consider. Hence, after having averaged over the inhomogeneous microstructure of the material, the heat producing nuclei are homogeneously distributed over the bodies. The heat production rate by these nuclear processes is

$$h_{\text{nuc}} = \sum_i \frac{X_{\text{el},i}}{m_{\text{el},i}} f_i \frac{E_i}{\tau_i} e^{-t/\tau_i}. \quad (27)$$

The sum is over all nuclei that contribute to heating, $X_{\text{el},i}$ denotes the mass-fraction of the corresponding element in the material of

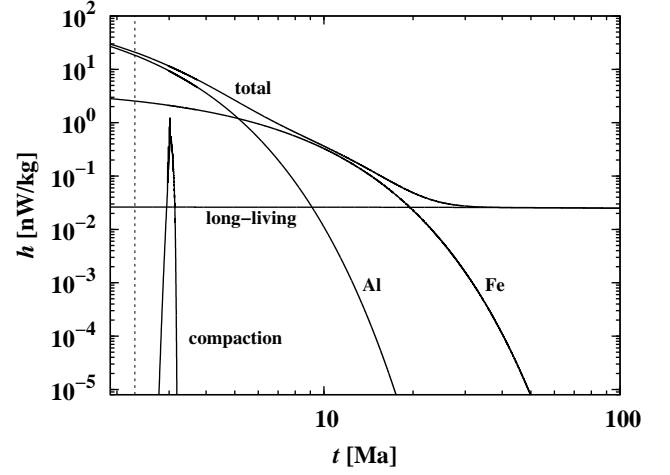


Fig. 4. Contributions of different heating mechanisms to the total heating rate. Time t is after formation of CAIs. The dashed line indicates the formation time of the H chondrite parent body (2.3 Ma, see Sect. 8). The release of gravitational energy by contraction is shown for the final model of the H chondrite parent body.

the planetesimals (see Table 2), $m_{\text{el},i}$ the atomic mass of the element for the isotopic mixture at the time of formation of the solar system, f_i the fraction of the isotope of interest at the time of formation of the solar system, τ_i the decay time scale for e-fold decrease of abundance of the isotope, and t is the time elapsed since formation of the solar system.

The constants for calculating h_{nuc} are given in Table 4. The element abundances used for calculating $X_{\text{el},i}$ for the mineral mixture given in Table 2 are taken from Lodders et al. (2009). Isotopic abundances of K and U at time of solar system formation are taken from Anders & Grevesse (1989). The abundance of ²⁶Al is that given by Nyquist et al. (2009). The abundance of ⁶⁰Fe is disputed in the literature. Table 4 gives the probably uppermost value from Birck & Lugmair (1988) and the lower limit according to Quitté et al. (2007). There are indications that ⁶⁰Fe was not homogeneously distributed in the early solar system (Quitté et al. 2010), which means that the initial ⁶⁰Fe abundance in the parent bodies is not known a priori and is an additional free parameter for the modelling. For the decay time of ⁶⁰Fe the recent revised value for the half-life $\tau_{1/2} = 2.62 \pm 0.04$ Ma of Rugel et al. (2009) is used.

Figure 4 shows the variation of the heating rate per unit mass with time elapsed since formation of CAI, calculated with the high ⁶⁰Fe abundance (see Table 4 for this). The dominant heating source is ²⁶Al at the time of formation of planetesimals ($t \lesssim 5$ Ma), but ⁶⁰Fe dominates as heat source for an extended period from ≈ 5 Ma to ≈ 20 Ma because of the revised ⁶⁰Fe half-life.

For comparison Fig. 4 also shows the contribution of the release of gravitational energy to heating during shrinking of the body, resulting for the model of Sect. 8. For the rather small bodies that are considered in this paper this heating source is not important (but included in the model).

5.4. Heat conduction by the porous solid material

For the heat conductivity K of the chondritic material we use two different types of experimental data. For low porosities from the range $0 < \phi \leq 0.2$ we use data measured for a number of ordinary H and L chondrites by Yomogida & Matsui (1983). For

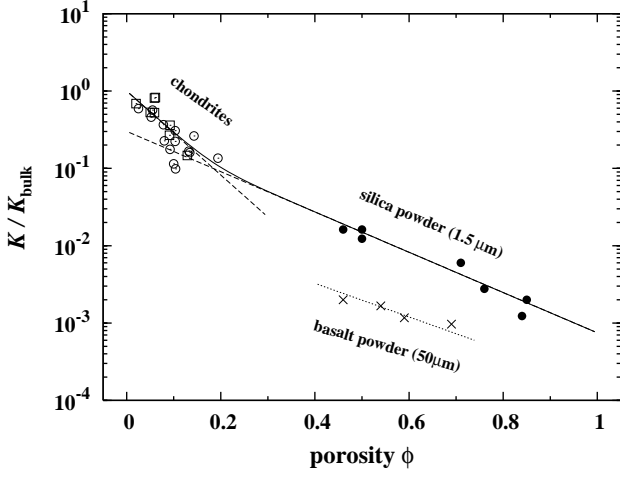


Fig. 5. Variation of heat conductivity K with porosity ϕ . Results for fine grained silica powder (filled circles) from experiments of Krause et al. (2011a,b), and for particulate basalt (crosses) from Fountain & West (1970). Typical grain size is indicated for both cases. Open squares and open circles are experimental results for heat conductivity and porosity for ordinary H and L chondrites, respectively, from (Yomogida & Matsui 1983). Solid line is analytic fit, Eq. (30), to the data.

high porosities $\phi > 0.4$ we use the data for silica powder derived from laboratory measurements by Krause et al. (2011a). All these measurements were conducted under vacuum conditions in order to exclude any contribution from heat transport from gas-fillings in the pores.

Figure 5 shows conductivity K plotted versus porosity for chondritic material at $T = 300$ K. The data for H and L chondrites scatter significantly and because of the small number of available data points no obvious systematic difference between the two types of material can be recognized. Therefore we fit both sets of data with a single analytic approximation

$$K_1(\phi) = K_b e^{-\phi/\phi_1} \quad (28)$$

with two constants K_b and ϕ_1 . This exponential form enables a reasonable fit of the data. The constant K_b may be interpreted as the extrapolated average thermal conductivity of the bulk material at vanishing porosity, for which we obtain $K_b = 4.3 \text{ W m}^{-1} \text{ K}^{-1}$. For the second constant we choose $\phi_1 = 0.08$ (see also Krause et al. 2011b). In Fig. (5) the data are normalized with the value of K_b . The dashed line running through the data points for the chondrites give our approximation $K_1(\phi)$.

At high porosities Fig. (5) shows the conductivity K for a silica powder that consists of equal sized spheres with $1.5 \mu\text{m}$ diameter. By the nature of the experimental method the data of Krause et al. (2011a) do not refer to a well defined temperature but the heat conductivity was derived by analysing the cooling behaviour of their sample. Therefore the value of K is some average value over the raise and fall of the temperature in the experiments, which is somewhat above room temperature. The data are fitted with an analytic approximation of the form

$$K_2(\phi) = K_b e^{a-\phi/\phi_2} \quad (29)$$

with two constants a and ϕ_1 and the same value of K_b as before. This type of exponential dependence on ϕ allows a reasonable fit of the data points also in this case. The constants are found to be $a = 1.2$ and $\phi_2 = 0.167$ (in an earlier version, Krause et al.

2011b, slightly different values of the constants were given). This fit is shown as the second dashed line in Fig. 5.

The experiments of Krause et al. (2011a) are conducted with very fine grained silica powder. This is not the same kind of material as it is found in chondrites, but for two reasons it may be considered as a reasonable proxy for chondrite material before strong compaction. First the mineral mix in chondrites is dominated by silicates and all silicates have similar heat conduction coefficients. Second the heat conduction of very loosely packed material is via the tiny contact regions between the particles. In chondrites part of the material are the rather big chondrules (size $\approx 1 \text{ mm}$), but as long as the material is not strongly compacted and the chondrules are well separated by the very small grained matrix (particle sizes $\leq 0.5 \mu\text{m}$), the heat conduction is obviously governed by the heat flow through the contact points between the tiny matrix particles. In this respect the basic physics of the heat transport in the experiment of Krause et al. (2011a) should be very similar to that in chondrite material before strong compaction.

The powder particles used in the experiments are about a factor of five to ten times bigger than the matrix particles in chondrites (Rietmeijer 1993). Some indications on the influence of particle sizes may be obtained by comparing the results of Krause et al. (2011a) with results of heat conduction measurements of Fountain & West (1970) for powders of basaltic particulates that are much coarser grained. Figure 5 shows results for their size separate with average particle size of $50 \mu\text{m}$. The variation of K with porosity for the Fountain & West (1970) granular material is very similar as of the silica powder used by Krause et al. (2011a), except that the conductivity is lower by a factor of somewhat less than a factor of ten. The particle sizes, on the other hand, are bigger on average by more than a factor of thirty. This suggests that the heat conductivity measured by Krause et al. (2011a) for the highly porous silica powder underestimates the conductivity of the matrix material of chondrites at the same porosity, but probably not by a big factor. In case of a power law dependence of K on particle sizes one may speculate that a by a factor of about three higher conductivity of meteoritic material than for the silica powder may be an appropriate estimation, but without more definite information we take the values of Krause et al. (2011a) for our model calculations.

The two fits, Eq. (28) and Eq. (29), for $\phi < 0.2$ and $\phi > 0.4$, respectively, are combined into a single analytic approximation for $K(\phi)$ by

$$K(\phi) = \left(K_1^4(\phi) + K_2^4(\phi) \right)^{1/4} \quad (30)$$

in order to smoothly interpolate between the two limit cases, in particular in the intermediate range of porosities $0.2 \leq \phi \leq 0.4$. This approximation is shown as the full line in Fig. 5.

The bulk conductivity K_b in Eq. (28) is temperature dependent. Figure 6 shows data for K for H and L chondrites as given by Yomogida & Matsui (1983), divided by $K_1(\phi)$, given by Eq. (28). The data for $K(T)/K_1(\phi)$ show for each of the meteorites a clear systematic variation with temperature. The extent of these variations, however, is much less than the scattering between the different meteorites which amounts to variations by a factor of about two. The origin of these meteorite-to-meteorite variations is not known, but most likely they have their origin in variations in the composition and structure of the meteoritic material. Such variations can presently not accurately be accounted for and will not be considered in our model calculations. Therefore we will also neglect the small variation of K with T and take K_b in our calculations to be temperature independent.

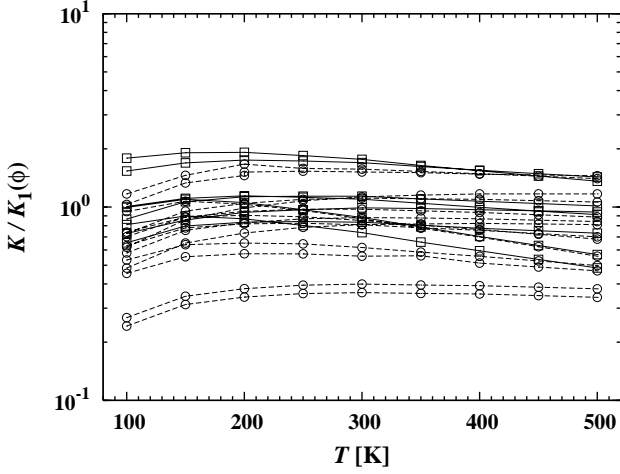


Fig. 6. Temperature variation of thermal conductivity K . Plotted are data for H chondrites (open rectangles) and L chondrites (open circles), normalized with the ϕ -variation according to approximation (28). The lines connect data for each of the meteorites.

5.5. Heat conduction by other processes

The material of the planetesimals is dominated by minerals that are transparent in the far infrared region. Therefore energy transport by radiation is possible. The energy flux by radiation increases strong with increasing temperature and for temperatures of the order of about 800 K and higher the heat flux by radiation becomes non-negligible. The complicated structure of the material (chondrules densely packed in a porous dust matrix) makes it difficult to calculate this from first principles. We follow therefore the proposal of Yomogida & Matsui (1984) to take the results of the laboratory measurements of Fountain & West (1970) of radiative heat conduction in basaltic powders as an approximation for meteoritic material. The model calculations show that for the bodies of interest (temperature stays below melting temperature) radiative heat conduction never becomes an important energy transport mode. This is because if temperature becomes high enough for radiative heat conduction to contribute somewhat to the net heat flux, the onset of sintering above ≈ 700 K results in a strong increase of heat conductivity by phonons that outnumbers radiative contributions again.

A possible contribution to heat conduction by pore gas is small and neglected in this paper; details of this will be discussed elsewhere.

5.6. Boundary conditions

For solving the heat conduction equation (23) one has to specify an initial condition $T(r, t_0)$ at some initial instant t_0 and boundary conditions, in our case at $r = 0$ and $r = R$.

The inner boundary condition is that there is no point source for heat at the centre which translates into the Neumann boundary condition

$$\left. \frac{\partial T}{\partial r} \right|_{r=0} = 0. \quad (31)$$

The temperature T_s of the surface layer of the body is determined by the equilibrium between (i) the energy fluxes toward the surface from the interior and from the outside, and (ii) the energy fluxes away from the surface to exterior space (cf., e.g.,

Grimm & McSween 1989; Ghosh et al. 2003). There results a mixed boundary condition at the surface

$$-K \left. \frac{\partial T}{\partial r} \right|_{r=R} = -\sigma_{\text{SB}} T_s^4 + F_{\text{ext}}. \quad (32)$$

The left hand side describes the energy flow from the interior toward the surface by heat conduction. The first term on the r.h.s. is the rate of energy loss by radiation from the surface to exterior space, the second term, F_{ext} , is the rate of energy gain by outer sources. During the first few million years, if the planetesimals are still embedded in an optically thick accretion disc, F_{ext} is given by $\sigma_{\text{SB}} T_c^4$, with T_c being the temperature at the midplane of the disk (see Fig. 1a). After disk dispersal the planetesimal is irradiated by the proto-sun and the rate of energy input, F_{ext} , is given by $(1 - A_{\text{surf}}) \sigma_{\text{SB}} T_*^4 R_p^2 / 4a^2$. Here a is the (average) distance to the star and A_{surf} is the albedo of the planetesimals surface.

Alternatively one can consider at the surface the Dirichlet condition

$$T(R) = T_b \quad (33)$$

with some prescribed value T_b . This has been done in a number of published model calculations where some fixed value for T_b was assumed.

5.7. Initial condition

Large planetesimals with radii of the order of 100 km occur as transition states during the growth from km sized bodies of the initial planetesimal swarm to protoplanets with sizes of the order of 1000 km. The growth initially proceeds rather slowly on timescales of a few 10^5 years until run-away growth commences after the biggest planetesimals reach sizes of about 10–20 km (e.g. Weidenschilling & Cuzzi 2006; Nagasawa et al. 2007). During run-away growth the mass rapidly increases within less than 10^5 years to the size of a protoplanet. This means that the bodies are formed on timescales shorter than the decay time of ≈ 1 Ma for ^{26}Al and also that they collect most of their mass within a period even much shorter than this. There is not sufficient time available for strong heating by ^{26}Al decay of those planetesimals that contributed to the growth of a 100 km sized body; most of the heat released by radioactive decay is released after its formation.

Therefore we will base our calculations in this paper on the “instantaneous formation” approximation where it is assumed that the body is formed within such a short period that all heating occurred after its formation. Within the framework of the instantaneous formation approximation it is appropriate to prescribe the temperature T_c of the disk material at the formation time of the planetesimals as initial value of the temperature.

Modifications resulting from a finite duration of the growth period will be considered elsewhere.

6. Sintering

The compaction of material in planetesimals is a two-step process. The initially very loosely packed dust material in the planetesimals comes under increasing pressure by the growing self-gravity of the bodies. The granular material can adjust by mutual gliding and rolling of the granular components to the exerted force and evolves into configurations with closer packing. The ongoing collisions with other bodies during the growth process enhances this kind of compaction of the material. This mode

of compaction, “cold pressing”, by its very nature does not depend on temperature and operates already at low temperature; it was considered in Sect. 4.2. A second mode of compaction commences if radioactive decays heat the planetesimal material to such an extent, that creep processes are thermally activated in the lattice of the solid material. The granular components then are plastically deformed under pressure and voids are gradually closed. This kind of compaction by “hot pressing” or “sintering” is what obviously operated in ordinary chondrite material and the different petrologic types 4 to 6 of chondrites are obviously different stages of compaction by hot pressing.

Yomogida & Matsui (1984) were the first to perform a quantitative study of this process by applying early theories of sintering developed in material science. We follow here essentially the same approach because more advanced modern theories of hot pressing are developed to model metallurgical processes that apply generally much higher pressures ($\gg 1$ kbar) than what is typically encountered in compaction of planetesimal material ($\lesssim 10^2$ bar) and are mainly concerned with the final stages of the process. Because the rate of increase of temperature in planetesimals is very low (of the order of 10^{-3} K yr $^{-1}$) the creep processes result in finite deformations of the material already at rather low temperatures or pressures, where under laboratory conditions no effect is seen. The more simple early theories of hot pressing seem better to fit to such situations.

6.1. Equations for hot pressing

For describing the sintering process we initially assume a dense packing of equal sized spheres with initial radius R_0 . The packing is sufficiently dense that no further compaction can be achieved by pressing without crushing the spheres. On average, the individual granular units will touch each other at Z contact points. At sufficiently high pressure and temperature the individual spheres will plastically deform at the contact points by creep processes and contact faces will form between adjacent particles while the volume of the particle will remain constant. As sintering proceeds, the voids between the spheres become smaller and the sphere centres get closer.

There are two stages for this process. In the first stage the voids form an interconnected network between the granular units. This closes at some stage of the sintering process and there remain isolated pores, that have to close by further sintering in a second stage. The relative density D at the transition between stages one and two depend on the type of packing. The following approximations are for the first stage.

The first basic assumption of the deformation theory of hot pressing by Kakar & Chaklader (1967), on which the work of Yomogida & Matsui (1984) is based, is a pure geometrical one. It is assumed that the formation of the contact faces can be conceived as if at each contact point a cap would have been cut-off from each of the two contacting grains. Then, for grains of equal radius, the contact areas are circular areas with radius a . It is assumed that all cut-away caps have the same height h and radius a at their base. The volume of one such cap is

$$V_{\text{cap}} = \frac{\pi}{6} h^2 (3R - h) \quad (34)$$

and its height

$$h = R - \sqrt{R^2 - a^2}. \quad (35)$$

The granular units then are (by assumption) spheres with Z caps cut-off from them. To conserve the original volume of the sphere,

the radius R of such a truncated sphere has to be bigger than the pristine radius R_0 . Conservation of volume requires

$$\frac{4\pi}{3} R_0^3 = \frac{4\pi}{3} R^3 - ZV_{\text{cap}}. \quad (36)$$

This holds as long as the contact areas do not come into contact with each other. The relation to the relative density D is (Kakar & Chaklader 1967)

$$\left(\frac{a}{R}\right)^2 = 1 - \left(\frac{R_0}{R}\right)^2 \left(\frac{D_0}{D}\right)^{2/3}. \quad (37)$$

Here D_0 is the relative density of the initial packing of spheres with radius R_0 . For a given number of contact points Z and given D_0 , R_0 , Eqs. (34) to (37) define R and a in terms of the relative density D .

In the theory of Rao & Chaklader (1972) a number of regular packings of spheres is considered for which the number of contact points Z is fixed ($Z = 6, 8, 12$). In particular they favour the ‘hexagonal prismatic’ packing with $Z = 8$ and gave their formula for this case. This is the model that has been used by Yomogida & Matsui (1984) in their study of sintering of planetesimals. They argued that many experiments on the packing of small spherical particles of constant size show that the porosity achieved after sufficient tapping would be near 40%, with an average of about eight contact points per particle. Since a regular hexagonal prismatic packing of spheres also has a coordination number of eight and a porosity of 39.5%, and a random close packing has porosity 36% and on average $Z = 7.3$ (see Sect. 3.2), they used that packing model in their sintering models. For a discussion of the more general case of random packings see, e.g., Arzt (1982); Arzt et al. (1983); Fischmeister & Arzt (1983); the equations obtained in that case are more involved, but there are no basic differences.

The second basic assumption in the theory of Rao & Chaklader (1972) of hot pressing is that the strain rate is related to the applied stress by the relation for power-law creep

$$\dot{\epsilon} = A\sigma_1^n, \quad (38)$$

and that $\dot{\epsilon}$ is given in terms of the rate of change of relative density as

$$\dot{\epsilon} = -\frac{\dot{D}}{D}. \quad (39)$$

The stress σ_1 is the pressure acting at the contact faces of the granular units. The quantities A and n have to be determined experimentally for each material. The quantity A depends on temperature.

The stress σ_1 is given by the pressure acting at the contact areas between the granular units. It is assumed that this is given in terms of the applied pressure p and the areas of contact faces, πa^2 , and average cross-section of the cell occupied by one granular unit, C_{av} , as

$$\pi a^2 \sigma_1 = C_{\text{av}} p. \quad (40)$$

In the hexagonal prismatic packing model favoured by Yomogida & Matsui (1984), the cross-section C_{av} is given by

$$C_{\text{av}} = 2\sqrt{3}(R^2 - a^2). \quad (41)$$

Via the dependence of R and a on D this is a function of D . Values for other packing models (e.g. Kakar & Chaklader 1967) are within $O(1)$ of this. In the initial stages of sintering (small

a) the stress σ_1 is much higher than p , in the final stages it approaches p .

Equations (38), (39), (40) result in the following differential equation for the relative density

$$\frac{\partial D}{\partial t} = -DA \left(\frac{C_{av}}{\pi a^2 p} \right)^n. \quad (42)$$

With the above relations between R , a and D this is a (closed) set of equations for calculating the time evolution of D , that has to be solved together with the other equations for the structure and evolution of the planetesimal which define the pressure and temperature.

The transition to stage 2 by closure of voids is assumed in models of hot pressing to occur at $D \gtrsim 0.9$ (e.g. Arzt et al. 1983). The equation for \dot{D} becomes $\dot{D} \propto 1 - D$ for this case (cf. Wilkinson & Ashby 1975; Arzt et al. 1983). Because the corresponding full equations are similar in structure to -Eq. (42) except for the factor $1 - D$ we include the final pore-closing stage simply by multiplying for $D > 0.9$ the r.h.s. of Eq. (42) by a factor

$$F = 10 \cdot (1 - D) \quad (D > 0.9), \quad (43)$$

to get a continuous transition between both cases.

6.2. Data for olivine

The pre-factor A and the power n in Eq. (38) have to be determined by laboratory exponents. Yomogida & Matsui (1984) used data from Schwenn & Goetze (1978) for olivine. No other data for materials of interest for planetesimals seem to have been determined since then. Schwenn & Goetze (1978) gave the following fit to their experimental data for small spheres of olivine ($R < 53, \mu\text{m}$):

$$\dot{\epsilon} = A \cdot \frac{\sigma^{3/2}}{R^3} e^{E_{act}/TR_{gas}}, \quad (44)$$

with σ stress on contact faces (in bar), E_{act} the activation energy for creep, T the temperature, R_{gas} the gas constant, and R the radius of granular units (in units cm).

For the activation energy a value of $E_{act} = 85 \pm 29 \text{ kcal mol}^{-1}$ was given by Schwenn & Goetze (1978). In the model calculations we use the value $E_{act} = 85 \text{ kcal mol}^{-1}$. For the pre-factor A a range of values from 1.6×10^{-5} to 5.4×10^{-5} was given by Schwenn & Goetze (1978); as a compromise we use a value of $A = 4 \times 10^{-5}$ in our model calculations.

Note that Yomogida & Matsui (1984) choose to use for $\dot{\epsilon}$ the approximation with $n = 1$ given in Eq. (7) in Schwenn & Goetze (1978), while we prefer to use the approximation given by Eq. (8) of Schwenn & Goetze (1978), because they explicitly state that this describes their measured σ -dependence.

7. Results for thermal evolution of planetesimals

7.1. Model calculation

The calculation of a model requires to solve the differential equations for heat conduction, Eq. (23), hydrostatic equilibrium, Eq. (7), for the evolution of porosity, Eq. (44), together with equations for the material properties, the equation of state, Eq. (3), the equations for heat conductivity, Eq. (30), and heat capacity, Eq. (26), and together with appropriate initial and boundary conditions.

Table 5. Model parameters for the model of Miyamoto et al. (1981) (MFT81) for a consolidated body (average L chondrite), and for a similar model of an initially porous body without (PL0) and with (PL) additional heating by decay of ^{60}Fe and long-lived nuclei.

Quantity		MFT81	PL0	PL	Units
radius	R	85	85	85	km
formation time	t_{form}	2.4	2.3	2.3	Ma
heat conductivity	K_b	1	4.3	4.3	$\text{W m}^{-1} \text{K}^{-1}$
surface temperature	T_s	180	150	150	K
density	ρ_{bulk}	3.2	3.59	3.59	g cm^{-3}
$^{26}\text{Al}/^{27}\text{Al}$		5	5.1	5.1	$\times 10^{-5}$
$^{60}\text{Fe}/^{56}\text{Fe}$		—	0	4.1	$\times 10^{-7}$
initial porosity	ϕ_{srf}	0 (10%)	60%	60%	

The heat conduction equation and the pressure equation are re-written in terms of M_r , defined by Eq. (8), as independent variable and are discretised for a set of fixed mass shells with masses ΔM_i ($i = 1, I$) and shell boundaries r_i ($i = 0, I$). The M_r -coordinate corresponds to a Lagrangean coordinate that is fixed to the matter. For this choice of coordinates there is no flow of matter across cell boundaries. This enables a simple treatment of growth of the body, if this is considered, and it avoids problems with numerical diffusion in case of inhomogeneous composition (e.g., radial variation of porosity).

The heat conduction equation is solved by a fully implicit finite difference method with Neumann boundary condition, Eq. (31), at centre and Dirichlet boundary condition, Eq. (33), at the surface. The first order ordinary differential equation for ϕ , Eq. (44), is solved by the fully implicit Euler method.

In order to account for the non-linear coupling between the different equations we perform a fixed-point iteration where we solve the equations in turn as follows:

1. Given are values of ϕ_i , T_i , ΔM_i for each mass shell i at some instant t_{k-1} . We have to calculate new values at next instant $t_k = t_{k-1} + \Delta t$. The values of ϕ_i , T_i at t_{k-1} are used as starting values for the iterative calculation of ϕ_i , T_i at t_k .
2. The heat production by radioactive decays over the period Δt is calculated for each shell.
3. For given porosity ϕ_i one finds ρ_i from Eq. (3) and with given mass ΔM_i in each mass shell i we calculate, starting from the centre, the shell boundaries r_i at t_k .
4. From the change of r_i over time Δt we find the grid velocity and the heat production by release of gravitational energy for each shell (last term in Eq. 23).
5. We calculate the pressures p_i at shell boundaries from the discretised pressure equation, starting with the given external pressure at the surface.
6. We solve for given temperatures T_i and pressure p_i at each grid-point Eq. (42) for the porosity over time interval Δt to determine an updated value of ϕ_i at t_k . The corresponding non-linear equations are solved iteratively with an accuracy of better than 10^{-12} .
7. We calculate from the updated porosity and pressure the heat conductivity.
8. We calculate for given T_i the heat capacity.
9. The surface temperature T_s is determined from Eq. (32). This equation is solved for T_s , using on the l.h.s. the values for T_i and K from the last iteration step.

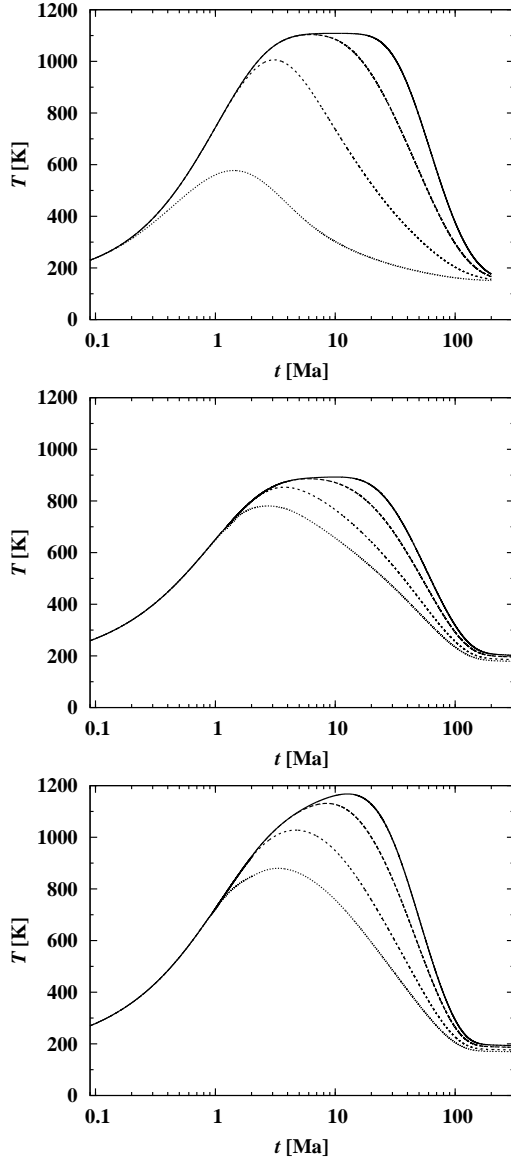


Fig. 7. Temperature evolution of a body of 85 km radius at different depths from the surface and at centre: Dotted line at depth 4.25 km, short dashed line at 17 km depth, long dashed line at 23 km depth. Full line shows temperature evolution at the centre. **(a)** The model is calculated with the same physical input as in the analytical model of Miyamoto et al. (1981). Model parameters MFT81 in Table 5. **(b)** Similar model, but now calculated for a porous body, considering thermal conductivity of porous material according to Eq. (30), and sintering and cold pressing as described in this paper. Model parameters PL0 in Table 5. **(c)** Same kind of model as (b), but now additional heating by ^{60}Fe and long-lived nuclei considered. Model parameters PL in Table 5.

10. Updated values of temperatures T_i at t_k are calculated for all i from the difference equations resulting from the heat conduction equation.
11. Check, if deviation of new values of T_i and ϕ_i at t_k from current values is sufficiently small.
12. If not, repeat calculation from step 3 on.
13. Otherwise determine new stepwidth Δt (see below), advance k by one, and repeat from step 1 on for the next time step.

This kind of iteration converges usually within about ten to twenty steps. The accuracy requirement was that the relative change of T_i , ϕ_i between subsequent iteration steps is less than 10^{-8} . This simple scheme works efficiently since the coefficients in the heat conduction equation do not strongly depend on temperature. Then this equation can be solved by the simple fixed-point iteration described. Test calculations done with complete linearisation of the non-linear equation showed that this did not significantly improve the efficiency of the solution method in our particular case. The advantage of our method is that it poses less stringent requirements on the existence and continuity of derivatives than the Newton-Raphson method for convergence of the iteration method.

The boundary condition given by Eq. (32) in principle should be built into the difference equations for the heat conduction equation. Numerical experience showed that this occasionally resulted in stability problems. Our present method is to solve Eq. (32) as a separate equation using at the current iteration step a value for the conductive heat flux at the surface calculated from the quantities of the last iteration step. The resulting value of T_s is prescribed as Dirichlet boundary condition, Eq. (33), for Eq. (23). The temperatures T_s calculated this way at each iteration step converge to the solution of Eq. (23) subject to Neumann boundary condition Eq. (32). This method worked without problems.

The time steps Δt are chosen such that the relative change of the variables over Δt is about 3%. This is sufficiently small that a further reduction of the stepwidth does not significantly improve the accuracy of the numerical solution; a reduction of the admitted stepwidth by a factor of two results in our case in relative changes of the numerical values of the variables by a few times of 10^{-4} . If the number of iteration steps becomes too big (e.g. > 20) with this choice, the stepwidth Δt is reduced by a factor of two until the number of iteration steps does no more exceed the limit. Since we use an implicit solution method, there is no limitation for the stepwidth from stability requirements.

The initial model for the start-up of the solution method assumes a fixed temperature ($= T_s$ at initial time) within the body. An appropriate set of masses ΔM_i is chosen that results (i) in a sufficiently fine grid at the surface to resolve the rapid temperature variations at the surface and that (ii) is sufficiently fine for allowing to calculate the derivative $\partial T / \partial M_r$ at the centre with sufficient accuracy. For the initial model the porosities ϕ_i and radii r_i for the set of mass-shells are calculated from hydrostatic equilibrium and the equation of state for cold pressing, as described in Sect. 4.2.

If a fixed temperature T_b is to be prescribed at the outer boundary, this is technically achieved within the frame of our solution algorithm by letting $F_{\text{ext}} = \sigma T_b^4$ in Eq. (32).

The solution method also allows to consider growing bodies by increasing the mass of the outermost shell according to some prescribed growth-law and splitting this shell into two shells at each instant where its mass exceeds some threshold value. This option in our code is not used, however, in the model calculations presented in this paper.

7.2. Some sample calculations

7.2.1. The model of Miyamoto et al.

As a first test we calculate with the code a model using the same model parameters as in Miyamoto et al. (1981). The basic parameters of the model are given in Table 5 in the column marked with MFT81. The model of Miyamoto et al. (1981) is one for a

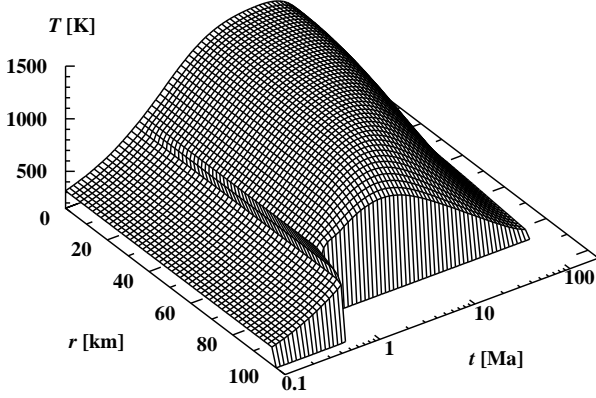


Fig. 8. Evolution of radial distribution of temperature for model PL (see Table 5 for its definition). Note the radial shrinking of the body by compaction of the initially porous material at about 0.6 decay timescales of ^{26}Al .

completely homogeneous body and does not consider the effects of porosity and the possibility of sintering. The data assumed for K and ρ correspond to average properties of L chondrites that, in fact, have low but non-vanishing porosities, scattering around about $\phi = 10\%$ (Yomogida & Matsui 1983). The true bulk density and heat conductivity of completely consolidated chondritic material is higher ($\rho_{\text{bulk}} = 3.6 \text{ g cm}^{-3}$, $K = 4.27 \text{ W kg}^{-1} \text{ K}^{-1}$, see Yomogida & Matsui (1983), their Table 5). The model is calculated by choosing as initial value $\phi = 0$ which guaranties that during the course of the calculation the porosity remains zero. Heating is only by decay of ^{26}Al . The result for the temperature evolution in the centre of the body and a number of selected radii is shown in Fig. 7a. This is almost identical with the result obtained by Miyamoto et al. (1981) from the analytic solution of the heat conduction equation, i.e., our code reproduces this exact analytic result.

7.2.2. Model of a porous body

In Fig. 7b we show the results for the temperature evolution of a body having the same size and using a similar set of parameters, but now considering that the heat conductivity of the porous material, Eq. (30), is different from the value of heat conductivity used by Miyamoto et al. (1981), and that the material from which the body forms is initially porous and consolidates by sintering. The parameters of the model are given in Table 5 in the column marked with PL0.

It is assumed that the porosity of the surface layers at low pressures is $\phi_{\text{srf}} = 0.6$, corresponding to the degree of compaction found in Weidling et al. (2009) for powder material that was subject to numerous impacts. This is what one expects for the early formation time of asteroids where they grow by repeated slow impacts of much smaller bodies. In deeper layers of the body where pressures are high due to self-gravity the material is compressed by isostatic pressing to higher densities up to a limiting value of $\phi \approx 0.4$, see Sect. 4.2. The corresponding initial distribution of porosities in the interior is calculated as described in Sect 4.2. For typical results see Fig. 2. This kind of compaction is a purely mechanical effect due to mutual rolling and gliding of the powder particles driven by an applied pressure which requires no elevated temperatures and acts therefore already in cold bodies (cold pressing). Starting from this ini-

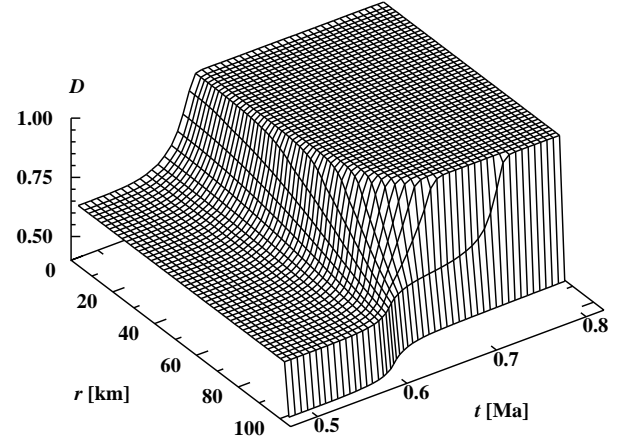


Fig. 9. Evolution of radial distribution of filling factor D (relative density) for model PL (see Table 5 for its definition). Shown is the very initial phase of the evolution where the initially porous material is compacted by sintering. The resulting shrinking of the planetesimal size occurs at about 0.6 decay timescales of ^{26}Al .

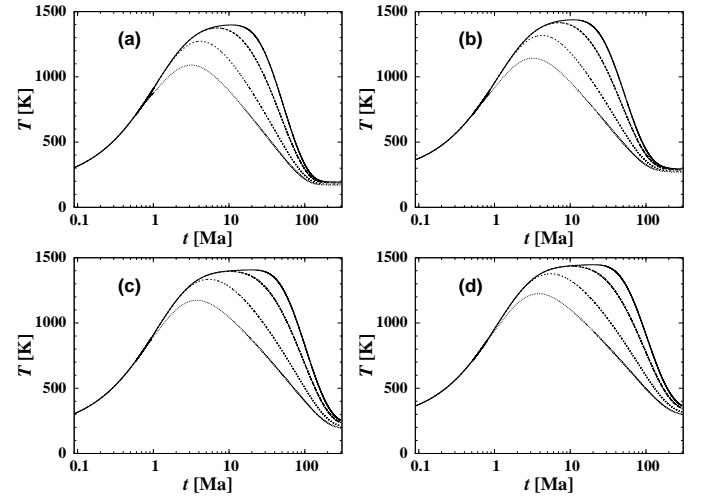


Fig. 10. Temperature evolution of test models for a porous bodies with modified values of parameters. Left panel with boundary temperature $T_b = 150 \text{ K}$, right panel with $T_b = 250 \text{ K}$. Upper panel with heat conduction coefficient $K_b = 4 \text{ W m}^{-1} \text{ K}^{-1}$, lower panel with $K_b = 2 \text{ W m}^{-1} \text{ K}^{-1}$.

tial configuration the evolution of the model was calculated. The porosity dependence of the heat conduction is taken into account by means of approximation Eq. (30). The surface temperature was taken to be constant over time and equal to $T_s = 150 \text{ K}$.

Figure 7b shows that the peak temperature achieved in the centre of the body is lower in this model than in the model of Miyamoto et al. (1981). This results from the higher heat conductivity in our model after complete sintering ($K_b = 4$ vs. $K_b = 1$). Contrary to this, the temperature in the outer layers of the model increases more rapidly than in the model of Miyamoto et al. (1981) because the high porosity outer layer acts as an insulating shield that prevents an efficient loss of heat to outer space. At a temperature of about 700–750 K (depending on pressure) sintering by hot pressing becomes active and the porosity rapidly approaches $\phi = 0$ at higher temperatures. The temperature structure then becomes nearly isothermal in the interior of the body and the temperature drops to the outer boundary

value within a layer of only a few km thickness. This is shown in detail in Fig. 8.

Figure 9 shows the evolution of the porosity during the earliest evolutionary phase. An outer shielding powder layer persists during the whole evolution of the body because cooling of the outer layers prevents the material to warm-up to the threshold temperature at about 750 K for compaction by hot pressing at low pressures. This behaviour is completely analogous to what is found in Yomogida & Matsui (1984) and can be compared with results by Sahijpal et al. (2007) and Gupta & Sahijpal (2010). They considered gradual sintering in the temperature range of 670–700 K by a smooth interpolation recipe, reducing the porosity from 55% to 0% by compaction of the body, and took into account respective changes in thermal diffusivity.

Because the porosity approaches zero everywhere in the body where the temperature exceeds the threshold for sintering by hot pressing, the radius of the body shrinks significantly, typically by 20% of its initial value. This occurs after about 0.6 decay timescales of the main heat source, ^{26}Al , in this model, cf. Figs. 8 and 9. The size of the model, marked as PL0 in Table 5, of 85 km corresponds to the final radius that the body would have after compaction to zero porosity (the initial radius before sintering is ≈ 105 km). The final radius of the body almost exactly equals the hypothetical final radius at zero porosity, since the powder layer remaining at the surface is rather thin. Also the temperatures shown in Fig. 7b for a number of depth points below the surface correspond to that Lagrangean M_r -coordinate, which after compression to zero porosity would have the given value of the radius coordinate. Before the body shrinks these points have somewhat bigger depths below the surface.

In Fig. 7c we show the temperature evolution in a model with the same set of parameters as the previous model (see Table 5, model PL), that considers heating by decay of ^{60}Fe and long-lived radioactive nuclei as additional heat sources, using an $^{60}\text{Fe}/^{56}\text{Fe}$ ratio at the upper limit of observed values (see Sect. 5.3). The peak central temperature is about 30% higher than without this heat source.

7.2.3. Mass-shells and time steps

Since in the present models the mass of the body is constant, a fixed grid of mass-shells is used in the calculations. This grid was constructed as follows: Starting from an outer layer with some (small) thickness, the thickness of the layers from the outside to the interior increases by a constant factor from one shell to next such that for some given number K of mass-shells the radius of the innermost sphere is 100 m; this fixes the width of the outermost layer. The models of this paper are calculated with $K = 300$, in which case the outermost layer has a thickness of ≈ 3 m. This choice of grid guarantees a sufficient high resolution of the thin outer region of rapid drop of temperature. An increase of K to 600 does not result in significant changes of the model characteristics; the relative change of central temperature, e.g., is $\approx 10^{-4}$.

In the model calculations used for fitting models to empirical cooling histories of meteorites described in Sect. 8, the total number K of shells is increased to $K = 1200$. This is necessary if one requires that even in the region of steepest temperature decrease toward the surface the relative changes of temperature at some fixed mass-coordinate are at most of the order of a few times 10^{-4} if the number of grid points is doubled.

The timesteps Δt are chosen according to the strategy described in Sect. 7.1. The timesteps during the initial heat-up phase were typically a few thousand years. Once sintering com-

mences, the step size decreases to about 100 years and varies around this value until complete sintering of the body (except for the outermost layers). Then Δt increases continuously and during the final phase is limited to a maximum value of 1 Ma in order to obtain not too widely spaced steps for plotting purposes. The total number of timesteps required for a complete model run for an evolution period of 100 Ma is between 3 500 and 4 000.

7.2.4. Dependence on parameters

In order to get an impression how the model depends on some important parameters, we show in Fig. 10 results for the same kind of model as model PL, but calculated with two different values of the surface temperature T_s and bulk heat conductivity coefficient K_b . The models in the left panel are calculated with a fixed surface temperature of 150 K, the models in the right panel with a fixed surface temperature of 250 K. These two values encompass the possible values of the surface temperature for bodies in the region of the asteroid belt for both cases, if either the body is embedded in the accretion disc (cf. Fig. 2) or the accretion disc has gone and the body is under the influence of the radiation of the young sun. There are only small differences between the run of the temperature at different depths, i.e., the temperature evolution below the immediate surface layer does not critically depend on the surface temperature, at least not for bodies with radii of the order of 100 km which are our main topic. Therefore we do not attempt in our further calculations to calculate T_s as precise as possible from Eq. (32) and simply assume a reasonable but fixed value for all times.

The upper panel in Fig. 10 is calculated with a value for the heat conduction coefficient of $K_b = 4 \text{ W m}^{-1} \text{ K}^{-1}$, the lower panel with $K_b = 2 \text{ W m}^{-1} \text{ K}^{-1}$. The first value corresponds to what has been found as the average value for H and L chondrites if measured values are extrapolated to zero porosity, see Sect. 5.4. As one can see from Fig. 6 there is significant scatter in the heat conduction coefficient (of presently unknown origin) and it is not clear whether the investigated sample of H and L chondrites are representative for the whole material of the parent body of the H or L chondrites. The value of $K_b = 4 \text{ W m}^{-1} \text{ K}^{-1}$ corresponds to typical values of K for pure silicate minerals (cf. Yomogida & Matsui 1983) and therefore probably represents the upper limit for the possible values of K_b . Lower values, therefore, may also be of interest for real planetesimals. Figure 10 shows that the results of the model calculation depend significantly on the value of K_b . Because it is presently not possible to determine K_b from first principles for chondritic material, we consider K_b in our later model calculations to be a free parameter (but, of course, restricted to the range of values found for chondrites).

7.3. Maximum central temperatures

The maximum central temperature that is reached during the course of the evolution of a planetesimal is an indicator of what kind of changes the material may undergo. If the central temperatures exceed the solidus temperature of chondritic material of about 1 400 K (Agee et al. 1995) partial melting occurs and the body starts to differentiate. If the temperature stays below the threshold temperature of about 700 K (at ≈ 0.1 bar) for sintering, the whole body retains its porous structure. The maximum central temperature $T_{c,\text{max}}$ depends mainly

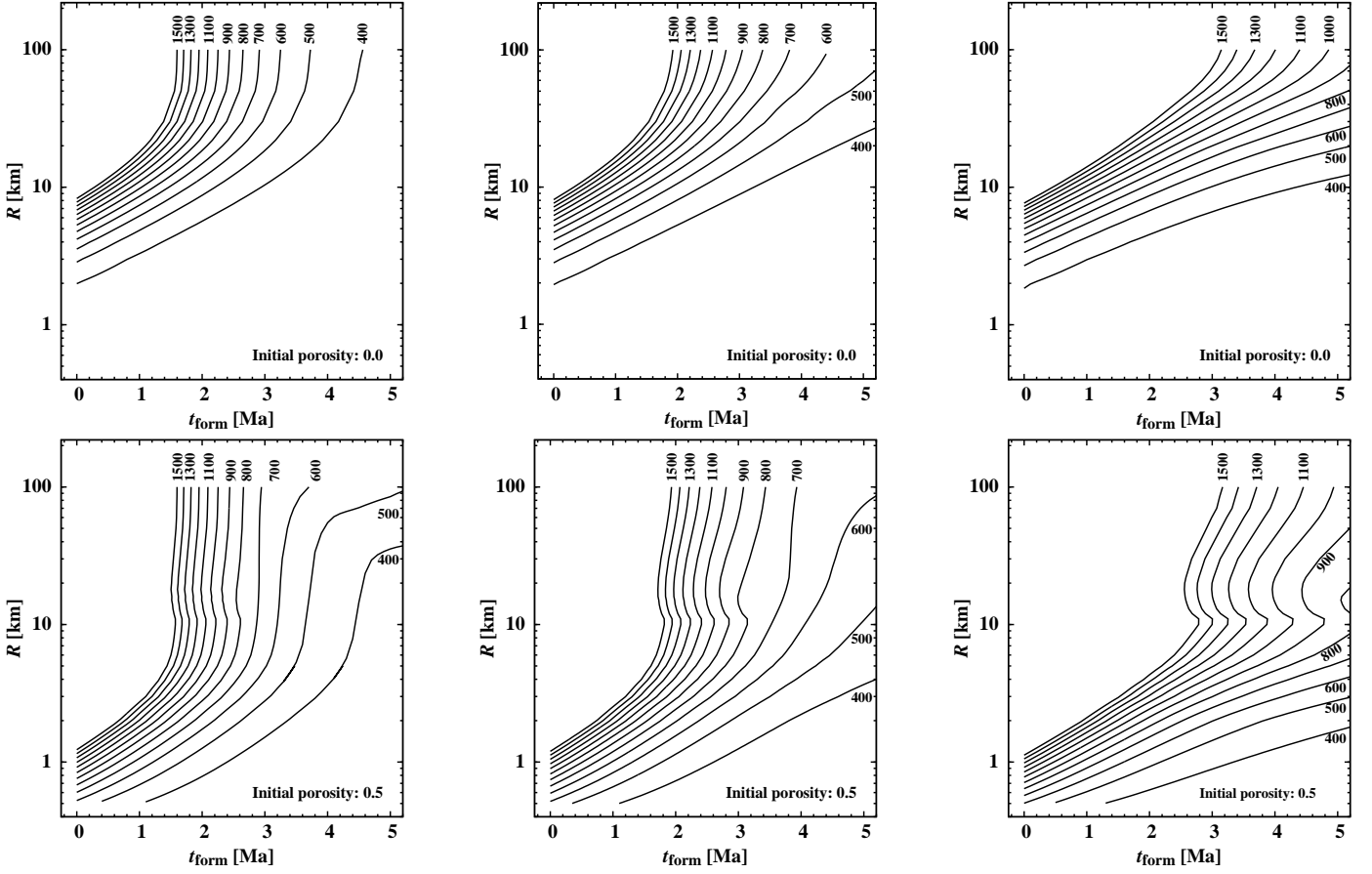


Fig. 11. Variation of maximum temperature in the centre of a planetesimal with radius R and instant of formation t_{form} . *Upper panel:* Completely consolidated bodies with porosity $\phi = 0$. *Lower panel:* Models of initially porous bodies with porosity $\phi_{\text{srf}} = 0.5$ which consolidate in the interior during the course of their thermal evolution. The lines correspond to the indicated maximum central temperature. At temperatures above $\approx 1\,400$ K partial melting of the mineral mixture is expected. Temperatures exceeding $1\,500$ K are left out for this reason. Shown are models for three different initial $^{60}\text{Fe}/^{56}\text{Fe}$ abundance ratios: *Left panel:* Without ^{60}Fe . *Middle panel:* The optimum fit value of 4.1×10^{-7} for the H chondrite parent body, see Sect. 8. *Right panel:* Highest value of 1.6×10^{-6} given in Table 5.

1. on the radius, R , of the body, because this determines how efficiently heat can be removed from the central region by heat conduction, and
2. on the formation time, t_{form} , because this determines how much of the initial inventory of radioactive material already decayed before the body grew to its final size.

Figure 11 shows the dependence of $T_{c,\text{max}}$ on R and t_{form} for models of initially porous bodies and, for comparison, of bodies with pore-free material. Obviously the thermal evolution history of initially porous bodies is very different from history of equal sized compact bodies. Models are shown for three different assumptions on the abundance of ^{60}Fe as additional heat source besides ^{26}Al .

For porous bodies smaller than ≈ 5 km radius the initial porosity is very high because they are even not compacted by cold pressing (cf. Fig. 2). Because of their low initial heat conductivity even rather small bodies ($R \gtrsim 0.5$ km) heat up at least to threshold temperature for sintering and become compacted in their interior, because the strongly insulating powder layer on their surface prevents their cooling. Completely compact bodies would reach central temperatures higher than 700 K only for radii exceeding ≈ 5 km because of much more efficient heat conduction.

For initially porous bodies bigger than ≈ 50 km radius already the initial porosity is low throughout almost all of the body because such bodies are already strongly compacted by cold pressing (cf. Fig. 2) and the remaining porosity rapidly disappears by sintering. Their thermal evolution is essentially identical to that of completely compact bodies, except, of course, in the layers close to the surface that retain part of their initial porosity.

Porous bodies with radii between ≈ 5 km and ≈ 20 km are already significantly compacted in their central part by cold pressing (cf. Fig. 2) but have initially an extended low-porosity outer mantle. Porous bodies with radii between ≈ 20 km and ≈ 50 km also are already compacted throughout the body by cold pressing (cf. Fig. 2), except for the outer $\approx 10\%$ of their radius. They show the most complex dependence of $T_{c,\text{max}}$ on R and formation time.

Temperatures above $T_{c,\text{max}} 1\,500$ K are not considered because we consider in this paper parent bodies of undifferentiated meteorites. At a temperature of $T_{c,\text{max}} \gtrsim 1\,400$ K the silicates start melting (Agee et al. 1995) and differentiation is unavoidable.

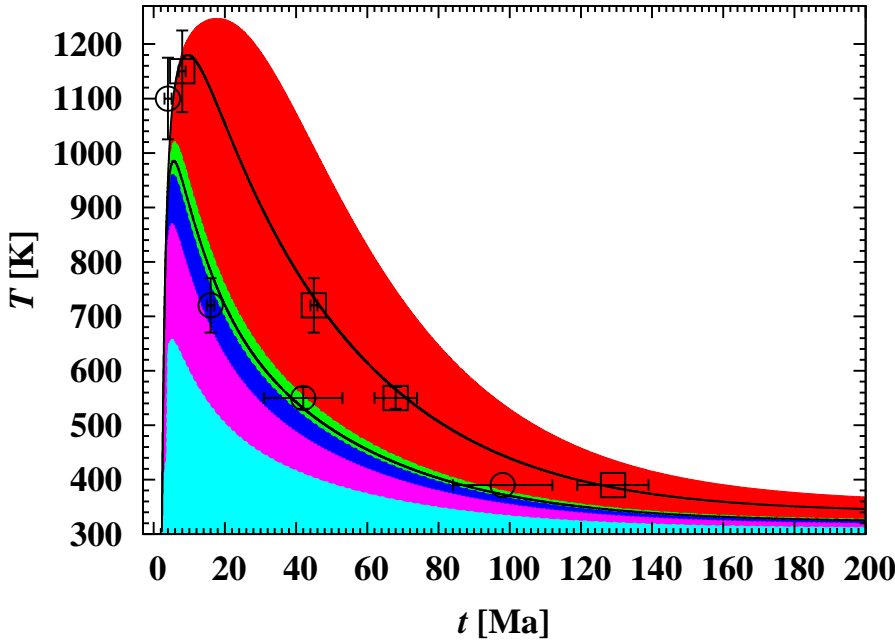


Fig. 12. Optimum-fit model for the cooling history of the parent body of H chondrites. Abscissa is time elapsed since formation CAIs. Evolution of temperature at a number of depths below the surface is shown. The upper contours of shaded areas correspond (from bottom to top) to depth's of 0.32 km, 2.3 km, 7.8 km, 11 km, and the uppermost contour to the centre. The rectangular boxes and circles correspond to the empirical data for H6 and H5 chondrites, respectively, given in Table 6. Crosses are error bars. The dashed lines correspond to the temperature evolution at depth's of 8.9 km (lower line) and 36 km (upper line) below the surface. They represent our best fit to the empirical data.

Table 6. Key data for cooling history of selected H chondrites

Quantity	Kernouvé	Richardton
type	H6	H5
	Hf-W ³ (metal-silicate)	
radiometric age	4559±1	4563±1
temperature	1150±75	1100±75
	U-Pb-Pb ³ (phosphates)	
radiometric age	4522±1	4551±1
temperature	720±50	720±50
	Ar-Ar ^{2,3} (feldspar)	
radiometric age	4499±6	4525±11
temperature	550±20	550±20
	Pu-fission tracks (pyroxene-merrillite)	
calculated age ⁴	4499±6	4525±11
cooling rate	2.6±0.5	2.9±0.5
calculated age ⁴	4438±10	4469±14
time interval ^{1,3}	61±8	56±9
	metallographic	
cooling rate ^{1,3}	10	20

Notes:

¹ Time-interval for Pu-fission track cooling rate from 550–390 K, metallographic cooling rate 800–600 K

² Recalculated for miscalibration of K decay constant (explanation see text and Tieloff et al. 2003)

³ Data from Hf-W: Kleine et al. (2008), U-Pb-Pb: (Göpel et al. 1994), Ar-Ar: Tieloff et al. (2003), metallographic cooling rates: Taylor et al. (1987)

⁴ Calculated age at 390 K from time interval between Pu-fission track (merrillite, 390 K) and Pu-fission tracks at 550 K (pyroxene) compared to Ar-Ar feldspar age at 550 K

8. Thermal history of the H chondrite parent body

8.1. Empirical data for cooling history

Most meteorites reach the Earth as cm- or m-sized rocks, as they are the result of repeated impact fragmentation of the initially much larger parent bodies. As such events can be highly energetic, they change both chemistry, structure, and also disturb the isotopic memory (i.e., the age information). Hence, information

Table 7. Properties of optimum fit model

Quantity	value	unit
Radius	R	100 km
formation time	t_{form}	2.3 Ma
heat conductivity	K_b	4.0 W m ⁻¹ K ⁻¹
surface temperature	T_s	300 K
⁶⁰ Fe/ ⁵⁶ Fe abundance ratio		4.1×10^{-7}
initial porosity	ϕ_{srf}	50%
Chondrite type	depth-range	
	from	to
powder layer	0.00	0.29
H3	0.29	2.3
H4	2.3	6.7
H5	6.7	10.8
H6	10.8	100
	burial depth	
Kernouvé	36	km
Richardton	8.3	km

of cooling histories extending back to the origin of the solar system must be restricted to meteorites that

1. show extraordinarily low mineralogical and structural characteristics of shock metamorphism induced by asteroid collisions,
2. were dated with high precision, and
3. were dated simultaneously by a set of various high and low temperature chronometers tracing the cooling history from high temperatures (> 1 000 K, e.g., Hf-W) down to intermediate (e.g. U-Pb-Pb or K-Ar) and very low temperatures (if possible < 400 K, e.g. ²⁴⁴Pu fission tracks).

Such high quality data on un-shocked chondrites are quite limited, in spite of the high number of meteorites available in terrestrial collections. While in the case of L chondrites, a major impact 470 Ma ago (Korochantseva et al. 2007) seems to have deeply erased the primordial low temperature cooling history, H

chondrites seem more promising. For a number of seven - noticeably un-shocked - H chondrites, complete high precision Hf-W, U-Pb-Pb, Ar-Ar and ^{244}Pu fission track data along with metallographic cooling rate data exist. Table 6 shows such data for the H6 chondrite Kernouvé and the H5 chondrite Richardton, which we can use for a preliminary sample calculation.

8.2. Fit of selected H chondrites

A "fit" to the data in Table 6 is shown in Fig. 12. The chronological data for these two meteorites best fit cooling curves in an asteroid at 36 and 8.9 km depth. The properties of the parent body in Table 7 were obtained according to the following fit-procedure: The initial abundance of ^{26}Al is roughly constrained by the $^{26}\text{Al}/^{27}\text{Al}$ ratio of ordinary chondrite chondrules, which is an upper limit shortly before parent body formation. Chondrule measurements indicate an ^{26}Al abundance corresponding roughly to 2-3 Ma formation time after CAIs. Similarly, the ^{60}Fe abundance is constrained by primitive type 3 ordinary chondrites (sulphides, see Tachibana & Huss 2003). Furthermore, abundances of ^{26}Al and ^{60}Fe (or, in other words, the formation time of the parent body) must be such that sufficiently high maximum metamorphic temperatures in the asteroid are achieved to allow strong type 6 metamorphism, but also not too high to prevent partial melting, metal silicate separation and differentiation. Heat conductivity and radius mainly influence the total duration of the cooling time of the parent body. We arbitrarily chose 100 km, although a smaller asteroid would also allow extended cooling as observed for Kernouvé, which in this model needs only a burial depth of about 36 km. The boundaries separating H6 from H5, H4 and H3 material are relatively shallow in the model, due to the insulating porous thin outer layer.

8.3. Discussion

The most prominent feature in our new model is the possibility of relatively small parent planetesimals with significant heat retention. In the H chondrite parent body model, this shows up in relatively thin layers of less heated or metamorphosed material. Moreover, the relatively fast cooling required to achieve temperatures below Hf-W and U-Pb-Pb closure for the H5 chondrite Richardton (within 3 and 13 Ma, respectively) sets an upper limit to the contribution of decay heat of ^{60}Fe (roughly about 20-30%). For example, if ^{60}Fe contributed all decay heat of ordinary chondrite parent body metamorphism, sufficient fast cooling of H5 metamorphosed material would not have been possible, as the half-life of ^{60}Fe is 2.6 Ma (a new revised value) versus 0.72 Ma for ^{26}Al , implying significantly longer heat production and implicit slower cooling in the first few Ma. This result is in line with the initial ^{60}Fe concentration found in primitive type 3 ordinary chondrites (Tachibana & Huss 2003), lower than initial values previously obtained for CAIs (Birck & Lugmair 1988), and supports the view that ^{60}Fe was likely not distributed homogeneously in the early solar system. A more detailed H chondrite parent body modeling will be presented elsewhere.

9. Concluding remarks

We constructed in this paper a model for the thermal evolution of the parent body of H chondrites. The model considers compaction by cold pressing and sintering by 'hot pressing'. The heat conductivity of the porous material was de-

termined by combining new data obtained by Krause et al. (2011a) for high porosity material with data for porous chondrites (Yomogida & Matsui 1983). A model was fitted to data on the cooling history for two H chondrites, Kernouvé (H6) and Richardton (H5), for which particular accurate data are available. It was shown that it is possible to find a consistent fit for the parent body size and formation time that reproduces with good accuracy the empirically determined cooling history of both, H5 and H6 chondrites.

For obtaining our consistent fit, it was necessary to include (besides radius of the body and formation time) also the abundance of ^{60}Fe into the fitting procedure. A value of $^{60}\text{Fe}/^{56}\text{Fe}$ was determined, that is within the range of values reported in the literature for different meteorites. No other arbitrary fit parameters are required; all other properties of the model are fixed by the physics of the problem.

The new model predicts rather shallow outer layers for petrologic types 3 to 5 because of the strong blanketing effect of an outer powder layer, that escapes sintering. In so far the model deviates considerable from previous models that are based on the analytic model of (Miyamoto et al. 1981). Other properties of the model are similar to older models; in particular radius and formation time are not substantially different.

The present model, though relaxing some earlier shortcomings, still has a number of shortcomings. The most stringent is the instantaneous formation hypothesis, that needs to be relaxed because the formation time of the body by run-away growth (of the order of 10^3 a) is shorter than the decay time of ^{26}Al , the main heating source, but probably not short enough for being completely negligible. The second severe shortcoming is that heat conductivity of porous media can not yet be treated from first principles on. This is not possible with presently available computing resources, but this may change in the near future. Other shortcomings are a rather simplistic treatment of sintering and of the outer boundary temperature. We modelled in this paper sintering with the same kind of theoretical description as Yomogida & Matsui (1984) in order that our results can be compared with that model. This treatment of sintering should be replaced by more elaborated modern theories of hot pressing.

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